# Comprehensive Triangular Decomposition 

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#### Abstract

We introduce the concept of comprehensive triangular decomposition (CTD) for a parametric polynomial system $F$ with coefficients in a field. In broad words, this is a finite partition of the the parameter space into regions, so that within each region the "geometry" (number of irreducible components together with their dimensions and degrees) of the algebraic variety of the specialized system $F(u)$ is the same for all values $u$ of the parameters.

We propose an algorithm for computing the CTD of $F$. It relies on a procedure for solving the following set theoretical instance of the coprime factorization problem. Given a family of constructible sets $A_{1}, \ldots, A_{s}$, compute a family $B_{1}, \ldots, B_{t}$ of pairwise disjoint constructible sets, such that for all $1 \leq i \leq s$ the set $A_{i}$ writes as a union of some of the $B_{1}, \ldots, B_{t}$.

We report on an implementation of our algorithm computing CTDs, based on the RegularChains library in Maple. We provide comparative benchmarks with MAPLE implementations of related methods for solving parametric polynomial systems. Our results illustrate the good performances of our CTD code.


## 1 Introduction

Solving polynomial systems with parameters has become an increasing need in several applied areas such as robotics, geometric modeling, stability analysis of dynamical systems and others. For a given parametric polynomial system $F$, the following problems are of interest.
(P1) Compute the values of the parameters for which $F$ has solutions, or has finitely many solutions.
(P2) Compute the solutions of $F$ as functions of the parameters.
These questions have been approached by various techniques including comprehensive Gröbner bases (CGB) [22|23|14|13|17], cylindrical algebraic decomposition (CAD) [4] and triangular decompositions [24|25|6|7|10|9|20|19|26|5]. Methods based on CGB, or more generally Gröbner bases, are powerful tools for solving problems such as (P1), that is, determining the values $u$ of the parameters such that, the specialized system $F(u)$ satisfies a given property. Methods based on CAD or triangular decompositions are naturally well designed for solving Problem (P2).

In this paper, we introduce the concept of comprehensive triangular decomposition for a parametric polynomial system with coefficients in a field. This notion plays the role for triangular decompositions that CGB does for Gröbner bases. With this concept
at hand, we show that Problems (P1) and (P2) can be completely answered by means of triangular decompositions.

Let $F$ be a finite set of polynomials with coefficients in a field $\mathbb{K}$, parameters $U=$ $U_{1}, \ldots, U_{d}$, and unknowns $X=X_{1}, \ldots, X_{m}$, that is, $F \subset \mathbb{K}\left[U_{1}, \ldots, U_{d}, X_{1}, \ldots, X_{m}\right]$. Let $\overline{\mathbb{K}}$ be the algebraic closure of $\mathbb{K}$, and let $\mathbf{V}(F) \subset \overline{\mathbb{K}}^{d+m}$ be the zero set of $F$. Let also $\Pi_{U}$ be the projection from $\overline{\mathbb{K}}^{d+m}$ on the parameter space $\overline{\mathbb{K}}^{d}$. For all $u \in \overline{\mathbb{K}}^{d}$ we define $\mathbf{V}(F(u)) \subseteq \overline{\mathbb{K}}^{m}$ the zero set defined by $F$ after specializing $U$ at $u$.

Our first contribution is to show how to compute a finite partition $\mathcal{C}$ of $\Pi_{U}(\mathbf{V}(F))$ and a family of triangular decompositions $\left(\mathcal{T}_{C}, C \in \mathcal{C}\right)$ in $\mathbb{K}[U, X]$ such that for each $C \in \mathcal{C}$ and for each parameter value $u \in C$ the triangular decomposition $\mathcal{T}_{C}$ specializes at $u$ into a triangular decomposition $\mathcal{T}_{C}(u)$ of $\mathbf{V}(F(u))$ given by regular chains. Moreover, each "cell" $C \in \mathcal{C}$ is a constructible set given by a family of regular systems in $\mathbb{K}[U]$. We call the pair $\left(\mathcal{T}_{C}, C \in \mathcal{C}\right)$ a comprehensive triangular decomposition of $\mathbf{V}(F)$, see Section 5

This is a natural definition inspired by that of a comprehensive Gröbner basis [22] introduced by Weispfenning with the additional requirements proposed by Montes in [14]. From each pair $\left(C, \mathcal{I}_{C}\right)$, we can read geometrical information, such as for which parameter values $u \in C$ the set $\mathbf{V}(F(u))$ is finite; we also obtain a "generic" equidimensional decomposition of $\mathbf{V}(F(u))$, for all $u \in C$. The notion of CTD is also related to the border polynomial of a polynomial system in [26] and the minimal discriminant variety of $\mathbf{V}(F)$ as defined in [12] for the case where $\overline{\mathbb{K}}$ is the field of complex numbers.

Example 1. Let $F=\left\{v x y+u x^{2}+x, u y^{2}+x^{2}\right\}$ be a parametric polynomial system with parameters $u>v$ and unknowns $x>y$. Then a comprehensive triangular decomposition of $\mathbf{V}(F)$ is:

$$
\begin{aligned}
C_{1}=\left\{u\left(u^{3}+v^{2}\right) \neq 0\right\}: & \mathcal{T}_{C_{1}}=\left\{T_{3}, T_{4}\right\} \\
C_{2}=\{u=0\}: & \mathcal{T}_{C_{2}}=\left\{T_{2}, T_{3}\right\} \\
C_{3}=\left\{u^{3}+v^{2}=0, v \neq 0\right\}: & \mathcal{T}_{C_{3}}=\left\{T_{1}, T_{3}\right\}
\end{aligned}
$$

where

$$
\begin{aligned}
& T_{1}=\left\{v x y+x-u^{2} y^{2}, 2 v y+1, u^{3}+v^{2}\right\} \\
& T_{2}=\{x, u\} \\
& T_{3}=\{x, y\} \\
& T_{4}=\left\{v x y+x-u^{2} y^{2}, u^{3} y^{2}+v^{2} y^{2}+2 v y+1\right\}
\end{aligned}
$$

Here, $C_{1}, C_{2}, C_{3}$ is a partition of $\Pi_{U}(\mathbf{V}(F))$ and $\mathcal{T}_{C_{i}}$ is a triangular decomposition of $\mathbf{V}(F)$ above $C_{i}$, for $i=1,2,3$. For different parameter values $u$, we can directly read geometrical information, such as the dimension of $\mathbf{V}(F(u))$.

By RegSer [19], $\mathbf{V}(F)$ can be decomposed into a set of regular systems:

$$
R_{1}=\left\{\begin{array}{r}
u x+v y+1=0 \\
\left(u^{3}+v^{2}\right) y^{2}+2 v y+1=0 \\
u\left(u^{3}+v^{2}\right) \neq 0
\end{array}, \quad R_{2}=\left\{\begin{array}{l}
x=0 \\
y=0 \\
u \neq 0
\end{array}\right.\right.
$$

$$
R_{3}=\left\{\begin{array}{r}
x=0 \\
v y+1=0 \\
u=0 \\
v \neq 0
\end{array}, R_{4}=\left\{\begin{array}{r}
2 u x+1=0 \\
2 v y+1=0 \\
u^{3}+v^{2}=0 \\
v \neq 0
\end{array}, \quad R_{5}=\left\{\begin{array}{l}
x=0 \\
u=0
\end{array}\right.\right.\right.
$$

For each regular system, one can directly read its dimension when parameters take corresponding values. However, the dimension of the input system could not be obtained immediately, since there is not a partition of the parameter space.

By DISPGB [14], one can obtain all the cases over the parameters leading to different reduced Gröbner bases with parameters:

$$
\begin{aligned}
& u\left(u^{3}+v^{2}\right) \neq 0:\left\{u x+\left(u^{3} v+v^{3}\right) y^{3}+\left(-u^{3}+v^{2}\right) y^{2},\left(u^{3}+v^{2}\right) y^{4}+2 v y^{3}+y^{2}\right\} \\
& u\left(u^{3}+v^{2}\right)=0, u \neq 0:\left\{u x+2 v^{2} y^{2}, 2 v y^{3}+y^{2}\right\} \\
& u=0, v \neq 0:\left\{x^{2}, v x y+x\right\} \\
& u=0, v=0:\{x\}
\end{aligned}
$$

Here for each parameter value, the input system specializes into a Gröbner basis. Since Gröbner bases do not necessarily have a triangular shape, the dimension may not be read directly either. For example, when $u=0, v \neq 0,\left\{x^{2}, v x y+x\right\}$ is not a triangular set.

In Section 5 we also propose an algorithm for computing the CTD of parametric polynomial system. We rely on an algorithm for computing the difference of the zero sets of two regular systems. Based on the procedures of the Triade algorithm [15] and elementary set theoretical considerations, such an algorithm could be developed straightforwardly. We actually tried this and our experimental results (not reported here) shows that this naive approach is very inefficient comparing to the more advanced algorithm presented in Section 3 Indeed, this latter algorithm heavily exploits the structure and properties of regular chains, whereas the former is unable to do so.

This latter procedure, is used to solve the following problem. Given a family of constructible sets, $A_{1}, \ldots, A_{s}$ (each of them given by a regular system) compute a family $B_{1}, \ldots, B_{t}$ of pairwise disjoint constructible sets, such that for all $1 \leq i \leq s$ the set $A_{i}$ writes as a union of some the $B_{1}, \ldots, B_{t}$. A solution is presented in Section 4 This can be seen as the set theoretical version of the coprime factorization problem, see [2|8] for other variants of this problem.

Our second contribution is an implementation report of our algorithm computing CTDs, based on the RegularChains library in Maple. We provide comparative benchmarks with MAPLE implementations of related methods for solving parametric polynomial systems, namely: decompositions into regular systems by Wang [19] and discussing parametric Gröbner bases by Montes [14]. We use a large set of well-known test-problems from the literature. Our implementation of the CTD algorithm can solve all problems which can be solved by the other methods. In addition, our CTD code can solve problems which are out of reach of the other two methods, generally due to memory consumption.

## 2 Preliminaries

In this section we introduce notations and review fundamental results in the theory of regular chains and regular systems [1|3|11|15|19|21].

We shall use some notions from commutative algebra (such as the dimension of an ideal) and refer for instance to [16] for this subject.

### 2.1 Basic Notations and Definitions

Let $\mathbb{K}[Y]:=\mathbb{K}\left[Y_{1}, \ldots, Y_{n}\right]$ be the polynomial ring over the field $\mathbb{K}$ in variables $Y_{1}<$ $\cdots<Y_{n}$. Let $p \in \mathbb{K}[Y]$ be a non-constant polynomial. The leading coefficient and the degree of $p$ regarded as a univariate polynomial in $Y_{i}$ will be denoted by $\operatorname{lc}\left(p, Y_{i}\right)$ and $\operatorname{deg}\left(p, Y_{i}\right)$ respectively. The greatest variable appearing in $p$ is called the main variable denoted by $\operatorname{mvar}(p)$. The degree, the leading coefficient, and the leading monomial of $p$ regarding as a univariate polynomial in $\operatorname{mvar}(p)$ are called the main degree, the initial, and the $r a n k$ of $p$; they are denoted by $\operatorname{mdeg}(p), \operatorname{init}(p)$ and $\operatorname{rank}(p)$ respectively.

Let $F \subset \mathbb{K}[Y]$ be a finite polynomial set. Denote by $\langle F\rangle$ the ideal it generates in $\mathbb{K}[Y]$ and by $\sqrt{\langle F\rangle}$ the radical of $\langle F\rangle$. Let $h$ be a polynomial in $\mathbb{K}[Y]$, the saturated ideal $\langle F\rangle: h^{\infty}$ of $\langle F\rangle$ w.r.t $h$, is the set

$$
\left\{q \in \mathbb{K}[Y] \mid \exists m \in \mathbb{N} \text { s.t. } h^{m} q \in\langle F\rangle\right\},
$$

which is an ideal in $\mathbb{K}[Y]$.
A polynomial $p \in \mathbb{K}[Y]$ is a zerodivisor modulo $\langle F\rangle$ if there exists a polynomial $q$ such that $p q$ is zero modulo $\langle F\rangle$, and $q$ is not zero modulo $\langle F\rangle$. The polynomial is regular modulo $\langle F\rangle$ if it is neither zero, nor a zerodivisor modulo $\langle F\rangle$. Denote by $\mathbf{V}(F)$ the zero set (or solution set, or algebraic variety) of $F$ in $\overline{\mathbb{K}}^{n}$. For a subset $W \subset \overline{\mathbb{K}}^{n}$, denote by $\bar{W}$ its closure in the Zariski topology, that is the intersection of all algebraic varieties $\mathbf{V}(G)$ containing $W$ for all $G \subset \mathbb{K}[Y]$.

Let $T \subset \mathbb{K}[Y]$ be a triangular set, that is a set of non-constant polynomials with pairwise distinct main variables. Denote by $\operatorname{mvar}(T)$ the set of main variables of $t \in T$. A variable in $Y$ is called algebraic w.r.t. $T$ if it belongs to mvar $(T)$, otherwise it is called free w.r.t. $T$. For a variable $v \in Y$ we denote by $T_{<v}$ (resp. $T_{>v}$ ) the subsets of $T$ consisting of the polynomials $t$ with main variable less than (resp. greater than) $v$. If $v \in \operatorname{mvar}(T)$, we say $T_{v}$ is defined. Moreover, we denote by $T_{v}$ the polynomial in $T$ whose main variable is $v$, by $T_{\leqslant v}$ the set of polynomials in $T$ with main variables less than or equal to $v$ and by $T \geqslant v$ the set of polynomials in $T$ with main variables greater than or equal to $v$.

Definition 1. Let $p, q \in \mathbb{K}[Y]$ be two nonconstant polynomials. We say $\operatorname{rank}(p)$ is smaller than $\operatorname{rank}(q)$ w.r.t Ritt ordering and we write, $\operatorname{rank}(p)<_{r} \operatorname{rank}(q)$ if one of the following assertions holds:

- mvar $(p)<\operatorname{mvar}(q)$,
$-\operatorname{mvar}(p)=\operatorname{mvar}(q)$ and $\operatorname{mdeg}(p)<\operatorname{mdeg}(q)$.
Note that the partial order $<_{r}$ is a well ordering. Let $T \subset \mathbb{K}[Y]$ be a triangular set. Denote by $\operatorname{rank}(T)$ the set of $\operatorname{rank}(p)$ for all $p \in T$. Observe that any two ranks in $\operatorname{rank}(T)$ are comparable by $<_{r}$. Given another triangular set $S \subset \mathbb{K}[Y]$, with $\operatorname{rank}(S) \neq$ $\operatorname{rank}(T)$, we write $\operatorname{rank}(T)<_{r} \operatorname{rank}(S)$ whenever the minimal element of the symmetric difference $(\operatorname{rank}(T) \backslash \operatorname{rank}(S)) \cup(\operatorname{rank}(S) \backslash \operatorname{rank}(T))$ belongs to $\operatorname{rank}(T)$. By
$\operatorname{rank}(T) \leqslant_{r} \operatorname{rank}(S)$, we mean either $\operatorname{rank}(T)<\operatorname{rank}(S)$ or $\operatorname{rank}(T)=\operatorname{rank}(S)$. Note that any sequence of triangular sets, of which ranks strictly decrease w.r.t $<_{r}$, is finite.

Given a triangular set $T \subset \mathbb{K}[Y]$, denote by $h_{T}$ be the product of the initials of $T$ (throughout the paper we use this convention and when $T$ consists of a single element $g$ we write it in $h_{g}$ for short). The quasi-component $\mathbf{W}(T)$ of $T$ is $\mathbf{V}(T) \backslash \mathbf{V}\left(h_{T}\right)$, in other words, the points of $\mathbf{V}(T)$ which do not cancel any of the initials of $T$. We denote by $\operatorname{Sat}(T)$ the saturated ideal of $T$ : if $T$ is empty then $\operatorname{Sat}(T)$ is defined as the trivial ideal $\langle 0\rangle$, otherwise it is the ideal $\langle T\rangle: h_{T}^{\infty}$.

Let $h \in \mathbb{K}[Y]$ be a polynomial and $F \subset \mathbb{K}[Y]$ a set of polynomials, we write

$$
\mathbf{Z}(F, T, h):=(\mathbf{V}(F) \cap \mathbf{W}(T)) \backslash \mathbf{V}(h)
$$

When $F$ consists of a single polynomial $p$, we use $\mathbf{Z}(p, T, h)$ instead of $\mathbf{Z}(\{p\}, T, h)$; when $F$ is empty we just write $\mathbf{Z}(T, h)$. By $\mathbf{Z}(F, T)$, we denote $\mathbf{V}(F) \cap \mathbf{W}(T)$.

Given a family of pairs $\mathbf{S}=\left\{\left[T_{i}, h_{i}\right] \mid 1 \leq i \leq e\right\}$, where $T_{i} \subset \mathbb{K}[Y]$ is a triangular set and $h_{i} \in \mathbb{K}[Y]$ is a polynomial. We write

$$
\mathbf{Z}(S):=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h_{i}\right)
$$

We conclude this section with some well known properties of ideals and triangular sets. For a proper ideal $\mathcal{I}$, we denote by $\operatorname{dim}(\mathbf{V}(\mathcal{I}))$ the dimension of $\mathbf{V}(\mathcal{I})$.

Lemma 1. Let $\mathcal{I}$ be a proper ideal in $\mathbb{K}[Y]$ and $p \in \mathbb{K}[Y]$ be a polynomial regular w.r.t $\mathcal{I}$. Then, either $\mathbf{V}(\mathcal{I}) \cap \mathbf{V}(p)$ is empty or we have: $\operatorname{dim}(\mathbf{V}(\mathcal{I}) \cap \mathbf{V}(p)) \leq \operatorname{dim}(\mathbf{V}(\mathcal{I}))-1$.
Lemma 2. Let $T$ be a triangular set in $\mathbb{K}[Y]$. Then, we have

$$
\overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h_{T}\right)=\mathbf{W}(T) \text { and } \overline{\mathbf{W}(T)} \backslash \mathbf{W}(T)=\mathbf{V}\left(h_{T}\right) \cap \overline{\mathbf{W}(T)}
$$

Proof. Since $\mathbf{W}(T) \subseteq \overline{\mathbf{W}(T)}$, we have

$$
\mathbf{W}(T)=\mathbf{W}(T) \backslash \mathbf{V}\left(h_{T}\right) \subseteq \overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h_{T}\right)
$$

On the other hand, $\overline{\mathbf{W}(T)} \subseteq \mathbf{V}(T)$ implies

$$
\overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h_{T}\right) \subseteq \mathbf{V}(T) \backslash \mathbf{V}\left(h_{T}\right)=\mathbf{W}(T)
$$

This proves the first claim. Observe that we have:

$$
\overline{\mathbf{W}(T)}=\left(\overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h_{T}\right)\right) \cup\left(\overline{\mathbf{W}(T)} \cap \mathbf{V}\left(h_{T}\right)\right)
$$

We deduce the second one.
Lemma 3 ([1]3]). Let $T$ be a triangular set in $\mathbb{K}[Y]$. Then, we have

$$
\mathbf{V}(\operatorname{Sat}(T))=\overline{\mathbf{W}(T)}
$$

Assume furthermore that $\mathbf{W}(T) \neq \emptyset$ holds. Then $\mathbf{V}(\operatorname{Sat}(T))$ is a nonempty unmixed algebraic set with dimension $n-|T|$. Moreover, if $N$ is the free variables of $T$, then for every prime ideal $\mathcal{P}$ associated with $\operatorname{Sat}(T)$ we have

$$
\mathcal{P} \cap \mathbb{K}[N]=\langle 0\rangle
$$

### 2.2 Regular Chain and Regular System

Definition 2 (Regular Chain). A triangular set $T \subset \mathbb{K}[Y]$ is a regular chain if one of the following conditions hold:

- either T is empty,
- or $T \backslash\left\{T_{\max }\right\}$ is a regular chain, where $T_{\max }$ is the polynomial in $T$ with maximum rank, and the initial of $T_{\max }$ is regular w.r.t. $\operatorname{Sat}\left(T \backslash\left\{T_{\max }\right\}\right)$.

It is useful to extend the notion of regular chain as follows.
Definition 3 (Regular System). A pair $[T, h]$ is a regular system if $T$ is a regular chain, and $h \in \mathbb{K}[Y]$ is regular w.r.t $\operatorname{Sat}(T)$.

Remark 1. A regular system in a stronger sense was presented in [19]. For example, consider the polynomial system $[T, h]$ where $T=\left[Y_{1} Y_{4}-Y_{2}\right]$ and $h=Y_{2} Y_{3}$. Then $[T, h]$ is still a regular system in our sense but not a regular system in Wang's sense. Also we do not restrict the main variables of polynomials in the inequality part. At least our definition is more convenient for our purpose in dealing with zerodivisors and conceptually clear as well. We also note that in the zerodimensional case (no free variables exist) the notion of regular chain and that of a regular set in [19] are the same, see 1.19] for details.

There are several equivalent characterizations of a regular chain, see [1]. In this paper, we rely on the notion of iterated resultant in order to derive a characterization which can be checked by solving a polynomial system.

Definition 4. Let $p \in \mathbb{K}[Y]$ be a polynomial and $T \subset \mathbb{K}[Y]$ be a triangular set. The iterated resultant of $p$ w.r.t. $T$, denoted by $\operatorname{res}(p, T)$, is defined as follows:

- if $p \in \mathbb{K}$ or all variables in $p$ are free w.r.t. $T$, then $\operatorname{res}(p, T)=p$,
- otherwise, if $v$ is the largest variable of $p$ which is algebraic w.r.t. $T$, then $\operatorname{res}(p, T)=\operatorname{res}\left(r, T_{<v}\right)$ where $r$ is the resultant of $p$ and the polynomial $T_{v}$.

Lemma 4. Let $p \in \mathbb{K}[Y]$ be a polynomial and $T \subset \mathbb{K}[Y]$ be a zerodimensional regular chain. Then the following statements are equivalent:
(i) The iterated resultant res $(p, T) \neq 0$.
(ii) The polynomial $p$ is regular modulo $\langle T\rangle$.
(iii) The polynomial $p$ is invertible modulo $\langle T\rangle$.

Proof. " $(i) \Rightarrow(i i)$ " Let $r:=\operatorname{res}(p, T)$. Then there exist polynomials $A_{i} \in \mathbb{K}[Y]$, $0 \leq i \leq n$, such that $r=A_{0} p+\sum_{i=1}^{n} A_{i} T_{i}$. So $r \neq 0$ implies $p$ is invertible modulo $\langle T\rangle$. Therefore, $p$ is regular modulo $\langle T\rangle$.
" $(i i) \Rightarrow($ iii $)$ " If $p$ is regular modulo $\langle T\rangle$, then $p$ is regular modulo $\sqrt{\langle T\rangle}$. Since $T$ is a zerodimensional regular chain, which implies $\operatorname{Sat}(T)=\langle T\rangle$, we know that $\mathbb{K}[Y] / \sqrt{\langle T\rangle}$ is a direct product of fields. Therefore $p$ is invertible modulo $\sqrt{\langle T\rangle}$, which implies $p$ is invertible modulo $\langle T\rangle$.
"(iii) $\Rightarrow(i)$ " Assume $\operatorname{res}(p, T)=0$, then we claim that $p$ and $T$ have at least one common solution, which is a contradiction to (iii).

We prove our claim by induction on $|T|$.
If $|T|=1$, we have two cases
(1) If all variables in $p$ are free w.r.t. $T$, then $\operatorname{res}(p, T)=p=0$. The claim holds.
(2) Otherwise, we have $\operatorname{res}(p, T)=\operatorname{res}(p, T, \operatorname{mar}(T))=0$. Since $\operatorname{init}(T) \neq 0$, the claim holds.

Now we assume that the claim holds for $|T|=n-1$. If $|T|=n$, let $v:=Y_{n}$. We have two cases
(1) If $v$ does not appear in $p$, then $\operatorname{res}(p, T)=\operatorname{res}\left(p, T_{<v}\right)$. By induction hypothesis, there exist $\xi_{1}, \xi_{2}, \cdots, \xi_{n-1} \in \overline{\mathbb{K}}$, such that $\xi^{\prime}=\left(\xi_{1}, \xi_{2}, \cdots, \xi_{n-1}\right)$ is a common solution of $p$ and $T_{<v}$. Since $T$ is a zerodimensional regular chain, $h_{T_{v}}$ is invertible modulo $\langle T\rangle$ (by " $(i i) \Rightarrow(i i i)$ " ). So $h_{T_{v}}\left(\xi^{\prime}\right) \neq 0$, which implies that there exists a $\xi_{n} \in \overline{\mathbb{K}}$, such that $\xi:=\left(\xi_{1}, \xi_{2}, \cdots, \xi_{n-1}, \xi_{n}\right)$ is a solution of $T_{v}$. Therefore $\xi$ is a common solution of $p$ and $T$.
(2) If $v$ appears in $p$, then $\operatorname{res}(p, T)=\operatorname{res}\left(\operatorname{res}\left(p, T_{v}, v\right), T_{<v}\right)=0$. Similarly to (1), there exists $\xi^{\prime}=\left(\xi_{1}, \xi_{2}, \cdots, \xi_{n-1}\right)$, such that $\operatorname{res}\left(p, T_{v}, v\right)\left(\xi^{\prime}\right)=T_{<v}\left(\xi^{\prime}\right)=0$ and $h_{T_{v}}\left(\xi^{\prime}\right) \neq 0$. So by the specialization property of resultant, $\operatorname{res}\left(p\left(\xi^{\prime}\right), T_{v}\left(\xi^{\prime}\right), v\right)=$ 0 , which implies that there exists a $\xi_{n} \in \overline{\mathbb{K}}$, such that $\xi:=\left(\xi_{1}, \xi_{2}, \cdots, \xi_{n-1}, \xi_{n}\right)$ is a common solution of $p$ and $T_{v}$. Therefore $\xi$ is a common solution of $p$ and $T$.

Theorem 1. The triangular set $T$ is a regular chain if and only if $\operatorname{res}\left(h_{T}, T\right) \neq 0$.
Proof. We start by assuming that $T$ is a zerodimensional regular chain, then the conclusion follows from Lemma 4

We reduce the general case to the zerodimensional one. First, we introduce a new total ordering $<_{T}$ on $Y$ defined as follows: if $Y_{i}$ and $Y_{j}$ are both in $\operatorname{mvar}(T)$ or both in its complement then $Y_{i}<_{T} Y_{j}$ holds if and only if $Y_{i}<Y_{j}$ holds, otherwise $Y_{i}<_{T} Y_{j}$ holds if and only if $Y_{j} \in \operatorname{mvar}(T)$. Clearly $T$ is also a triangular set w.r.t $<_{T}$. We observe that $h_{T}$, and thus $\operatorname{Sat}(T)$, are unchanged when replacing the variable ordering $<$ by $<_{T}$. Similarly, it is easy to check that a polynomial $p \in \mathbb{K}[Y]$ reduces to zero by pseudo-division by $T$ w.r.t. $<$ if and only if it reduces to zero by pseudodivision by $T$ w.r.t. $<_{T}$. Therefore, by applying Theorem 6.1 [1] we deduce that $T$ is a regular chain w.r.t. $<$ if and only if it is a regular chain w.r.t. $<_{T}$. Similarly, we have $\operatorname{res}\left(h_{T}, T\right) \neq 0$ w.r.t. $<$ if and only if $\operatorname{res}\left(h_{T}, T\right) \neq 0$ w.r.t. $<_{T}$.

Now we assume that the variables are ordered according to $<_{T}$. Let $N$ be the set of the variables of $Y$ that do not belong to $\operatorname{mvar}(T)$. The triangular set $T$ is a regular chain in $\mathbb{K}[Y]$ if and only if it is a zerodimensional regular chain when regarded as a triangular set in $\mathbb{K}(N)[Y \backslash N]$ (where $\mathbb{K}(N)$ denotes the field of rational functions with coefficients in $\mathbb{K}$ and variables in $N$ ). This is Corollary 3.2 in [3]. Similarly, it is easy to check that $\operatorname{res}\left(h_{T}, T\right) \neq 0$ holds when regarding $T$ in $\mathbb{K}[Y]$ if and only if $\operatorname{res}\left(h_{T}, T\right) \neq 0$ holds when regarding $T$ in $\mathbb{K}(N)[Y \backslash N]$.

Proposition 1. For every regular system $[T, h]$ we have $\mathbf{Z}(T, h) \neq \emptyset$.

Proof. Since $T$ is a regular chain, by Lemma 3 we have $\mathbf{V}(\operatorname{Sat}(T)) \neq \emptyset$. By definition of regular system, the polynomial $h h_{T}$ is regular w.r.t $\operatorname{Sat}(T)$. Hence, by Lemma 1 the set $\mathbf{V}\left(h h_{T}\right) \cap \mathbf{V}(\operatorname{Sat}(T))$ either is empty, or has lower dimension than $\mathbf{V}(\operatorname{Sat}(T))$. Therefore, the set

$$
\mathbf{V}(\operatorname{Sat}(T)) \backslash \mathbf{V}\left(h h_{T}\right)=\mathbf{V}(\operatorname{Sat}(T)) \backslash\left(\mathbf{V}\left(h h_{T}\right) \cap \mathbf{V}(\operatorname{Sat}(T))\right)
$$

is not empty. Finally, by Lemma2 the set

$$
\mathbf{Z}(T, h)=\mathbf{W}(T) \backslash \mathbf{V}(h)=\overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h h_{T}\right)=\mathbf{V}(\operatorname{Sat}(T)) \backslash \mathbf{V}\left(h h_{T}\right)
$$

is not empty.
Notation 1. For a regular system $R=[T, h]$, we define $\operatorname{rank}(R):=\operatorname{rank}(T)$. For a set $\mathcal{R}$ of regular systems, we define

$$
\operatorname{rank}(\mathcal{R}):=\max \{\operatorname{rank}(T) \mid[T, h] \in \mathcal{R}\}
$$

For a pair of regular systems $(L, R)$, we define $\operatorname{rank}((L, R)):=(\operatorname{rank}(L), \operatorname{rank}(R))$. For a pair of lists of regular systems, we define

$$
\operatorname{rank}((\mathcal{L}, \mathcal{R}))=(\operatorname{rank}(\mathcal{L}), \operatorname{rank}(\mathcal{R}))
$$

For triangular sets $T, T_{1}, \ldots, T_{e}$ we write $\mathbf{W}(T) \xrightarrow{D}\left(\mathbf{W}\left(T_{i}\right), i=1 \ldots\right.$ e) if one of the following conditions holds:

- either $e=1$ and $T=T_{1}$,
- or $e>1, \operatorname{rank}\left(T_{i}\right)<\operatorname{rank}(T)$ for all $i=1 \ldots e$ and

$$
\mathbf{W}(T) \subseteq \bigcup_{i=1}^{e} \mathbf{W}\left(T_{i}\right) \subseteq \overline{\mathbf{W}(T)}
$$

### 2.3 Triangular Decompositions

Definition 5. Given a finite polynomial set $F \subset \mathbb{K}[Y]$, a triangular decomposition of $\mathbf{V}(F)$ is a finite family $\mathcal{T}$ of regular chains of $\mathbb{K}[Y]$ such that

$$
\mathbf{V}(F)=\bigcup_{T \in \mathcal{T}} \mathbf{W}(T)
$$

For a finite polynomial set $F \subset \mathbb{K}[Y]$, the Triade algorithm [15] computes a triangular decomposition of $\mathbf{V}(F)$. We list below the specifications of the operations from Triade that we use in this paper.

Let $p, p_{1}, p_{2}$ be polynomials, and let $T, C, E$ be regular chains such that $C \cup E$ is a triangular set (but not necessarily a regular chain).

- Regularize $(p, T)$ returns regular chains $T_{1}, \ldots, T_{e}$ such that
- $\mathbf{W}(T) \xrightarrow{D}\left(\mathbf{W}\left(T_{i}\right), i=1 \ldots e\right)$,
- for all $1 \leq i \leq e$ the polynomial $p$ is either 0 or regular modulo $\operatorname{Sat}\left(T_{i}\right)$.
- For a set of polynomials $F$, Triangularize $(F, T)$ returns regular chains $T_{1}, \ldots, T_{e}$ such that we have

$$
\mathbf{V}(F) \cap \mathbf{W}(T) \subseteq \mathbf{W}\left(T_{1}\right) \cup \cdots \cup \mathbf{W}\left(T_{e}\right) \subseteq \mathbf{V}(F) \cap \overline{\mathbf{W}(T)}
$$

and for $1 \leq i \leq e$ we have $\operatorname{rank}\left(T_{i}\right)<\operatorname{rank}(T)$.

- $\operatorname{Extend}(C \cup E)$ returns a set of regular chains $\left\{C_{i} \mid i=1 \ldots e\right\}$ such that we have $\mathbf{W}(C \cup E) \xrightarrow{D}\left(\mathbf{W}\left(C_{i}\right), i=1 \ldots e\right)$.
- Assume that $p_{1}$ and $p_{2}$ are two non-constant polynomials with the same main variable $v$, which is larger than any variable appearing in $T$, and assume that the initials of $p_{1}$ and $p_{2}$ are both regular w.r.t. $\operatorname{Sat}(T)$. Then, $\mathbf{G C D}\left(p_{1}, p_{2}, T\right)$ returns a sequence

$$
\left(\left[g_{1}, C_{1}\right], \ldots,\left[g_{d}, C_{d}\right],\left[\emptyset, D_{1}\right], \ldots,\left[\emptyset, D_{e}\right]\right)
$$

where $g_{i}$ are polynomials and $C_{i}, D_{i}$ are regular chains such that the following properties hold:

- $\mathbf{W}(T) \xrightarrow{D}\left(\mathbf{W}\left(C_{1}\right), \ldots, \mathbf{W}\left(C_{d}\right), \mathbf{W}\left(D_{1}\right), \ldots, \mathbf{W}\left(D_{e}\right)\right)$,
- $\operatorname{dim} \mathbf{V}\left(\operatorname{Sat}\left(C_{i}\right)\right)=\operatorname{dim} \mathbf{V}(\operatorname{Sat}(T))$ and $\operatorname{dim} \mathbf{V}\left(\operatorname{Sat}\left(D_{j}\right)\right)<\operatorname{dim} \mathbf{V}(\operatorname{Sat}(T))$, for all $1 \leqslant i \leqslant d$ and $1 \leqslant j \leqslant e$,
- the leading coefficient of $g_{i}$ w.r.t. $v$ is regular w.r.t. Sat $\left(C_{i}\right)$,
- for all $1 \leqslant i \leqslant d$ there exist polynomials $u_{i}$ and $v_{i}$ such that we have $g_{i}=$ $u_{i} p_{1}+v_{i} p_{2} \bmod \operatorname{Sat}\left(C_{i}\right)$,
- if $g_{i}$ is not constant and its main variable is $v$, then $p_{1}$ and $p_{2}$ belong to $\operatorname{Sat}\left(C_{i} \cup\left\{g_{i}\right\}\right)$.


### 2.4 Constructible Sets

Definition 6 (Constructible set). A constructible subset of $\overline{\mathbb{K}}^{n}$ is any finite union

$$
\left(A_{1} \backslash B_{1}\right) \cup \cdots \cup\left(A_{e} \backslash B_{e}\right)
$$

where $A_{1}, \ldots, A_{e}, B_{1}, \ldots, B_{e}$ are algebraic varieties in $\overline{\mathbb{K}}^{n}$.
Lemma 5. Every constructible set can write as a union of zero sets of regular systems.
Proof. By the definition of constructible set, we only need to prove that the difference of two algebraic varieties can write as a union of zero sets of regular systems. Let $\mathbf{V}(F), \mathbf{V}(G)$, where $F, G \subset \mathbb{K}[Y]$, be two algebraic varieties in $\overline{\mathbb{K}}^{n}$. With the Triangularize operation introduced in last subsection, we write $\mathbf{V}(F)$ as a union of the zero sets of some regular systems

$$
\mathbf{V}(F)=\bigcup_{i=1}^{s} \mathbf{W}\left(T_{i}\right)=\bigcup_{i=1}^{s} \mathbf{Z}\left(T_{i}, 1\right)
$$

Similarly, we can write $\mathbf{V}(G)$ as

$$
\mathbf{V}(G)=\bigcup_{i=1}^{t} \mathbf{Z}\left(C_{i}, 1\right)
$$

Then the conclusion follows from the algorithm DifferenceLR introduced in next section.

## 3 The Difference Algorithms

In this section, we present an algorithm to compute the set theoretical difference of two constructible sets given by regular systems. As mentioned in the Introduction, a naive approach appears to be very inefficient in practice. Here we contribute a more sophisticated algorithm, which heavily exploits the structure and properties of regular chains.

Two procedures, Difference and DifferenceLR, are involved in order to achieve this goal. Their specifications and pseudo-codes can be found below. The rest of this section is dedicated to proving the correctness and termination of these algorithms. For the pseudo-code, we use the Maple syntax. However, each of the two functions below returns a sequence of values. Individual value or sub-sequences of the returned sequence are thrown to the flow of output by means of an output statement. Hence an output statement does not cause the termination of the function execution.

## Algorithm 1 Difference $\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)$

Input $[T, h],\left[T^{\prime}, h^{\prime}\right]$ two regular systems.
Output Regular systems $\left\{\left[T_{i}, h_{i}\right] \mid i=1 \ldots e\right\}$ such that

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h_{i}\right)
$$

and $\operatorname{rank}\left(T_{i}\right) \leqslant_{r} \operatorname{rank}(T)$.
Algorithm 2 DifferenceLR $(\mathcal{L}, \mathcal{R})$
Input $\mathcal{L}:=\left\{\left[L_{i}, f_{i}\right] \mid i=1 \ldots r\right\}$ and $\mathcal{R}:=\left\{\left[R_{j}, g_{j}\right] \mid j=1 \ldots s\right\}$ two lists of regular systems.
Output Regular systems $\mathcal{S}:=\left\{\left[T_{i}, h_{i}\right] \mid i=1 \ldots e\right\}$ such that

$$
\left(\bigcup_{i=1}^{r} \mathbf{Z}\left(L_{i}, f_{i}\right)\right) \backslash\left(\bigcup_{j=1}^{s} \mathbf{Z}\left(R_{j}, g_{j}\right)\right)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h_{i}\right)
$$

with $\operatorname{rank}(\mathcal{S}) \leqslant_{r} \operatorname{rank}(\mathcal{L})$.
To prove the termination and correctness of above two algorithms, we present a series of technical lemmas.

Lemma 6. Let $p$ and $h$ be polynomials and $T$ a regular chain. Assume that $p \notin \operatorname{Sat}(T)$. Then there exists an operation $\operatorname{Intersect}(p, T, h)$ returning a set of regular chains $\left\{T_{1}, \ldots, T_{e}\right\}$ such that
(i) $h$ is regular w.r.t $\operatorname{Sat}\left(T_{i}\right)$ for all $i$;
(ii) $\operatorname{rank}\left(T_{i}\right){<_{r}}_{r} \operatorname{rank}(T)$;
(iii) $\mathbf{Z}(p, T, h) \subseteq \cup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h\right) \subseteq(\mathbf{V}(p) \cap \overline{\mathbf{W}(T)}) \backslash \mathbf{V}(h)$;
(iv) Moreover, if the product of initials $h_{T}$ of $T$ divides $h$ then

$$
\mathbf{Z}(p, T, h)=\bigcup_{i=1}^{e} \mathbf{Z}\left(T_{i}, h\right)
$$

```
Algorithm 1. Difference \(\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\)
    if \(\operatorname{Sat}(T)=\operatorname{Sat}\left(T^{\prime}\right)\) then
        output Intersect \(\left(h^{\prime} h_{T^{\prime}}, T, h h_{T}\right)\)
    else
        Let \(v\) be the largest variable s.t. \(\operatorname{Sat}\left(T_{<v}\right)=\operatorname{Sat}\left(T_{<v}^{\prime}\right)\)
        if \(v \in \operatorname{mvar}\left(T^{\prime}\right)\) and \(v \notin \operatorname{mvar}(T)\) then
            \(p^{\prime} \leftarrow T_{v}^{\prime}\)
            output \(\left[T, h p^{\prime}\right]\)
            output DifferenceLR(Intersect \(\left.\left(p^{\prime}, T, h h_{T}\right),\left[T^{\prime}, h^{\prime}\right]\right)\)
        else if \(v \notin \operatorname{mvar}\left(T^{\prime}\right)\) and \(v \in \operatorname{mvar}(T)\) then
            \(p \leftarrow T_{v}\)
            output DifferenceLR \(\left([T, h]\right.\), \(\left.\operatorname{Intersect}\left(p, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)\right)\)
        else
            \(p \leftarrow T_{v}\)
            \(\mathcal{G} \leftarrow \mathbf{G C D}\left(T_{v}, T_{v}^{\prime}, T_{<v}\right)\)
            if \(|\mathcal{G}|=1\) then
                Let \((g, C) \in \mathcal{G}\)
                if \(g \in \mathbb{K}\) then
                    output \([T, h]\)
                else if mvar \((g)<v\) then
                    output \([T, g h]\)
                    output DifferenceLR(Intersect \(\left.\left(g, T, h h_{T}\right),\left[T^{\prime}, h^{\prime}\right]\right)\)
                else if \(\operatorname{mvar}(g)=v\) then
                    if \(\operatorname{mdeg}(g)=\operatorname{mdeg}(p)\) then
                        \(D_{p}^{\prime} \leftarrow T_{<v}^{\prime} \cup\{p\} \cup T_{>v}^{\prime}\)
                    output Difference \(\left([T, h],\left[D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right]\right)\)
                    else if \(\operatorname{mdeg}(g)<\operatorname{mdeg}(p)\) then
                    \(q \leftarrow \operatorname{pquo}(p, g, C)\)
                    \(D_{g} \leftarrow C \cup\{g\} \cup T_{>v}\)
                    \(D_{q} \leftarrow C \cup\{q\} \cup T_{>v}\)
                    output Difference \(\left(\left[D_{g}, h h_{T}\right],\left[T^{\prime}, h^{\prime}\right]\right)\)
                    output Difference \(\left(\left[D_{q}, h h_{T}\right],\left[T^{\prime}, h^{\prime}\right]\right)\)
                    output DifferenceLR(Intersect \(\left.\left(h_{g}, T, h h_{T}\right),\left[T^{\prime}, h^{\prime}\right]\right)\)
                    end if
                end if
            else if \(|\mathcal{G}| \geq 2\) then
                for \((g, C) \in \mathcal{G}\) do
                    if \(|C|>\left|T_{<v}\right|\) then
                    for \(E \in \operatorname{Extend}(C, T \geqslant v)\) do
                        for \(D \in \operatorname{Regularize}\left(h h_{T}, E\right)\) do
                                    if \(h h_{T} \notin \operatorname{Sat}(D)\) then
                                    output Difference \(\left(\left[D, h h_{T}\right],\left[T^{\prime}, h^{\prime}\right]\right)\)
                                    end if
                                    end for
                    end for
                    else
                            output Difference \(\left(\left[C \cup T_{\geqslant v}, h h_{T}\right],\left[T^{\prime}, h^{\prime}\right]\right)\)
                    end if
                end for
            end if
        end if
    end if
```

```
Algorithm 2. DifferenceLR \((L, R)\)
    if \(L=\emptyset\) then
        output \(\emptyset\)
    else if \(R=\emptyset\) then
        output \(L\)
    else if \(|R|=1\) then
        Let \(\left[T^{\prime}, h^{\prime}\right] \in R\)
        for \([T, h] \in L\) do
            output Difference([T, \(\left.h],\left[T^{\prime}, h^{\prime}\right]\right)\)
        end for
    else
        while \(R \neq \emptyset\) do
            Let \(\left[T^{\prime}, h^{\prime}\right] \in R, R \leftarrow R \backslash\left\{\left[T^{\prime}, h^{\prime}\right]\right\}\)
            \(S \leftarrow \emptyset\)
            for \([T, h] \in L\) do
                \(S \leftarrow S \cup\) Difference \(\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\)
            end for
            \(L \leftarrow S\)
        end while
        output \(L\)
    end if
```

Proof. Let

$$
\begin{aligned}
\mathcal{S} & =\operatorname{Triangularize}(p, T) \\
\mathcal{R} & =\bigcup_{C \in \mathcal{S}} \operatorname{Regularize}(h, C)
\end{aligned}
$$

We then have

$$
\mathbf{V}(p) \cap \mathbf{W}(T) \subseteq \bigcup_{R \in \mathcal{R}} \subseteq \mathbf{V}(p) \cap \overline{\mathbf{W}(T)}
$$

This implies

$$
\mathbf{Z}(p, T, h) \subseteq \bigcup_{R \in \mathcal{R},} \bigcup_{\notin \operatorname{Sat}(R)} \mathbf{Z}(R, h) \subseteq(\mathbf{V}(p) \cap \overline{\mathbf{W}(T)}) \backslash \mathbf{V}(h)
$$

Rename the regular chains $\{R \mid R \in \mathcal{R}, h \notin \operatorname{Sat}(R)\}$ as $\left\{T_{1}, \ldots, T_{e}\right\}$. By the specification of Regularize we immediately conclude that ( $i$ ), (iii) hold. Since $p \notin \operatorname{Sat}(T)$, by the specification of Triangularize, (ii) holds. By Lemma2, (iv) holds.

Lemma 7. Let $[T, h]$ and $\left[T^{\prime}, h^{\prime}\right]$ be two regular systems. If $\operatorname{Sat}(T)=\operatorname{Sat}\left(T^{\prime}\right)$, then $h^{\prime} h_{T^{\prime}}$ is regular w.r.t $\operatorname{Sat}(T)$ and

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(h^{\prime} h_{T^{\prime}}, T, h h_{T}\right)
$$

Proof. Since $\operatorname{Sat}(T)=\operatorname{Sat}\left(T^{\prime}\right)$ and $h^{\prime} h_{T^{\prime}}$ is regular w.r.t $\operatorname{Sat}\left(T^{\prime}\right), h^{\prime} h_{T^{\prime}}$ is regular w.r.t $\operatorname{Sat}(T)$. By Lemma 2 and Lemma3, we have

$$
\begin{aligned}
\mathbf{Z}\left(T, h h^{\prime} h_{T^{\prime}}\right) & =\mathbf{W}(T) \backslash \mathbf{V}\left(h h^{\prime} h_{T^{\prime}}\right) \\
& =\overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h h^{\prime} h_{T} h_{T^{\prime}}\right) \\
& =\overline{\mathbf{W}\left(T^{\prime}\right)} \backslash \mathbf{V}\left(h h^{\prime} h_{T} h_{T^{\prime}}\right) \\
& =\mathbf{W}\left(T^{\prime}\right) \backslash \mathbf{V}\left(h h^{\prime} h_{T}\right) \\
& =\mathbf{Z}\left(T^{\prime}, h h^{\prime} h_{T}\right) .
\end{aligned}
$$

Then, we can decompose $\mathbf{Z}(T, h)$ into the disjoint union

$$
\mathbf{Z}(T, h)=\mathbf{Z}\left(T, h h^{\prime} h_{T^{\prime}}\right) \bigsqcup \mathbf{Z}\left(h^{\prime} h_{T^{\prime}}, T, h h_{T}\right)
$$

Similarly, we have:

$$
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(T^{\prime}, h h^{\prime} h_{T}\right) \bigsqcup \mathbf{Z}\left(h h_{T}, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

The conclusion follows from the fact that

$$
\mathbf{Z}\left(T, h h^{\prime} h_{T^{\prime}}\right) \backslash \mathbf{Z}\left(T^{\prime}, h h^{\prime} h_{T}\right)=\emptyset \quad \text { and } \quad \mathbf{Z}\left(h^{\prime} h_{T^{\prime}}, T, h h_{T}\right) \cap \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\emptyset
$$

Lemma 8. Assume that $\operatorname{Sat}\left(T_{<v}\right)=\operatorname{Sat}\left(T_{<v}^{\prime}\right)$. We have
(i) If $p^{\prime}:=T_{v}^{\prime}$ is defined but not $T_{v}$, then $p^{\prime}$ is regular w.r.t $\operatorname{Sat}(T)$ and

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(T, h p^{\prime}\right) \bigsqcup\left(\mathbf{Z}\left(p^{\prime}, T, h h_{T}\right) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)\right)
$$

(ii) If $p:=T_{v}$ is defined but not $T_{v}^{\prime}$, then $p$ is regular w.r.t $\operatorname{Sat}\left(T^{\prime}\right)$ and

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(p, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

Proof. (i) As $\operatorname{init}\left(p^{\prime}\right)$ is regular w.r.t $\operatorname{Sat}\left(T_{<v}^{\prime}\right)$, it is also regular w.r.t $\operatorname{Sat}\left(T_{<v}\right)$. Since $T_{v}$ is not defined, we know $v \notin \operatorname{mvar}(T)$. Therefore, $p^{\prime}$ is also regular w.r.t $\operatorname{Sat}(T)$. On the other hand, we have a disjoint decomposition

$$
\mathbf{Z}(T, h)=\mathbf{Z}\left(T, h p^{\prime}\right) \bigsqcup \mathbf{Z}\left(p^{\prime}, T, h h_{T}\right)
$$

By the definition of $p^{\prime}, \mathbf{Z}\left(T^{\prime}, h^{\prime}\right) \subseteq \mathbf{V}\left(p^{\prime}\right)$ which implies

$$
\mathbf{Z}\left(T, h p^{\prime}\right) \bigcap \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\emptyset
$$

The conclusion follows.
(ii) Similarly, we know $p$ is regular w.r.t $\operatorname{Sat}\left(T^{\prime}\right)$. By the disjoint decomposition

$$
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(T^{\prime}, h^{\prime} p\right) \bigsqcup \mathbf{Z}\left(p, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

and $\mathbf{Z}(T, h) \cap \mathbf{Z}\left(T^{\prime}, h^{\prime} p\right)=\emptyset$, we have

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(p, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

from which the conclusion follows.

Lemma 9. Assume that $\operatorname{Sat}\left(T_{<v}\right)=\operatorname{Sat}\left(T_{<v}^{\prime}\right)$ but $\operatorname{Sat}\left(T_{\leqslant v}\right) \neq \operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right)$ and that $v$ is algebraic w.r.t both $T$ and $T^{\prime}$. Define

$$
\begin{aligned}
\mathcal{G} & =\mathbf{G C D}\left(T_{v}, T_{v}^{\prime}, T_{<v}\right) ; \\
\mathcal{E} & =\bigcup_{(g, C) \in \mathcal{G},|C|>\left|T_{<v}\right|} \operatorname{Extend}\left(C, T_{\geqslant v}\right) ; \\
\mathcal{R} & =\bigcup_{E \in \mathcal{E}} \operatorname{Regularize}\left(h h_{T}, E\right) .
\end{aligned}
$$

Then we have
(i)

$$
\begin{aligned}
& \mathbf{Z}(T, h) \\
& =\left(\bigcup_{R \in \mathcal{R}, h h_{T} \notin \operatorname{Sat}(R)} \mathbf{Z}\left(R, h h_{T}\right)\right) \bigcup\left(\bigcup_{(g, C) \in \mathcal{G},|C|=\left|T_{<v}\right|} \mathbf{Z}\left(C \cup T_{\geqslant v}, h h_{T}\right)\right) .
\end{aligned}
$$

(ii) $\operatorname{rank}(R)<_{r} \operatorname{rank}(T)$, for all $R \in \mathcal{R}$.
(iii) Assume that $|C|=\left|T_{<v}\right|$. Then
(iii.a) $C \cup T_{\geqslant v}$ is a regular chain and $h h_{T}$ is regular w.r.t it.
(iii.b) If $|\mathcal{G}|>1$, then $\operatorname{rank}\left(C \cup T_{\geqslant v}\right)<_{r} \operatorname{rank}(T)$.

Proof. By the specification of GCD we have

$$
\mathbf{W}\left(T_{<v}\right) \subseteq \bigcup_{(g, C) \in \mathcal{G}} \mathbf{W}(C) \subseteq \overline{\mathbf{W}\left(T_{<v}\right)} .
$$

That is,

$$
\mathbf{W}\left(T_{<v}\right) \xrightarrow{D}(\mathbf{W}(C),(g, C) \in \mathcal{G}) .
$$

From the specification of Extend we have: for each $(g, C) \in \mathcal{G}$ such that $|C|>\left|T_{<v}\right|$,

$$
\mathbf{W}\left(C \cup T_{\geqslant v}\right) \xrightarrow{D}\left(\mathbf{W}(E), E \in \mathbf{E x t e n d}\left(C \cup T_{\geqslant v}\right)\right) .
$$

From the specification of Regularize, we have for all $(g, C) \in \mathcal{G}$ such that $|C|>$ $\left|T_{<v}\right|$ and all $E \in \operatorname{Extend}\left(C \cup T_{\geqslant v}\right)$,

$$
\mathbf{W}(E) \xrightarrow{D}\left(\mathbf{W}(R), R \in \operatorname{Regularize}\left(h h_{T}, E\right)\right) .
$$

Therefore, by applying the Lifting Theorem [15] we have:

$$
\begin{aligned}
\mathbf{W}(T) & =\mathbf{W}\left(T_{<v} \cup T_{\geqslant v}\right) \\
& \subseteq\left(\bigcup_{R \in \mathcal{R}} \mathbf{W}(R)\right) \bigcup\left(\bigcup_{(g, C) \in \mathcal{G},|C|=\left|T_{<v}\right|} \mathbf{W}\left(C \cup T_{\geqslant v}\right)\right) \\
& \subseteq \overline{\mathbf{W}\left(T_{<v} \cup T_{\geqslant v}\right)} \\
& =\overline{\mathbf{W}(T)},
\end{aligned}
$$

which implies,

$$
\begin{aligned}
& \mathbf{Z}(T, h)=\mathbf{Z}\left(T, h h_{T}\right) \\
& \subseteq\left(\bigcup_{R \in \mathcal{R}, h h_{T} \notin \operatorname{Sat}(R)} \mathbf{Z}\left(R, h h_{T}\right)\right) \bigcup\left(\bigcup_{(g, C) \in \mathcal{G},|C|=\left|T_{<v}\right|} \mathbf{Z}\left(C \cup T_{\geqslant v}, h h_{T}\right)\right) \\
& \subseteq \overline{\mathbf{W}(T)} \backslash \mathbf{V}\left(h h_{T}\right)=\mathbf{Z}(T, h) .
\end{aligned}
$$

So (i) holds. When $|\mathcal{G}|>1$, by Notation 1 (ii) and (iii.b) hold. If $|C|=\left|T_{<v}\right|$, by Proposition 5 of [15], we conclude that (iii.a) holds.

Lemma 10. Assume that $\operatorname{Sat}\left(T_{<v}\right)=\operatorname{Sat}\left(T_{<v}^{\prime}\right)$ but $\operatorname{Sat}\left(T_{\leqslant v}\right) \neq \operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right)$ and that $v$ is algebraic w.r.t both $T$ and $T^{\prime}$. Define $p=T_{v}, p^{\prime}=T_{v}^{\prime}$ and

$$
\mathcal{G}=\mathbf{G C D}\left(p, p^{\prime}, T_{<v}\right)
$$

If $|\mathcal{G}|=1$, let $\mathcal{G}=\{(g, C)\}$. Then the following properties hold
(i) $C=T_{<v}$.
(ii) If $g \in \mathbb{K}$, then

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}(T, h)
$$

(iii) If $g \notin \mathbb{K}$ and $\operatorname{mvar}(g)<v$, then $g$ is regular w.r.t $\operatorname{Sat}(T)$ and

$$
\begin{aligned}
& \mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right) \\
& =\mathbf{Z}(T, g h) \bigsqcup\left(\mathbf{Z}\left(g, T, h h_{T}\right) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)\right)
\end{aligned}
$$

(iv) Assume that $\operatorname{mvar}(g)=v$.
(iv.a) If $\operatorname{mdeg}(g)=\operatorname{mdeg}(p)$, defining

$$
\begin{aligned}
q^{\prime} & =\operatorname{pquo}\left(p^{\prime}, p, T_{<v}^{\prime}\right) \\
D_{p}^{\prime} & =T_{<v}^{\prime} \cup\{p\} \cup T_{>v}^{\prime} \\
D_{q^{\prime}}^{\prime} & =T_{<v}^{\prime} \cup\left\{q^{\prime}\right\} \cup T_{>v}^{\prime},
\end{aligned}
$$

then we have

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

$\operatorname{rank}\left(D_{p}^{\prime}\right)<\operatorname{rank}\left(T^{\prime}\right)$ and $h^{\prime} h_{T^{\prime}}$ is regular w.r.t $\operatorname{Sat}\left(D_{p}^{\prime}\right)$.
(iv.b) If $\operatorname{mdeg}(g)<\operatorname{mdeg}(p)$, defining

$$
\begin{aligned}
q & =\operatorname{pquo}\left(p, g, T_{<v}\right) \\
D_{g} & =T_{<v} \cup\{g\} \cup T_{>v} \\
D_{q} & =T_{<v} \cup\{q\} \cup T_{>v},
\end{aligned}
$$

then we have: $D_{g}$ and $D_{q}$ are regular chains such that $\operatorname{rank}\left(D_{g}\right)<\operatorname{rank}(T)$, $\operatorname{rank}\left(D_{q}\right)<\operatorname{rank}(T), h h_{T}$ is regular w.r.t $\operatorname{Sat}\left(D_{g}\right)$ and $\operatorname{Sat}\left(D_{q}\right)$, and

$$
\mathbf{Z}(T, h)=\mathbf{Z}\left(D_{g}, h h_{T}\right) \bigcup \mathbf{Z}\left(D_{q}, h h_{T}\right) \bigcup \mathbf{Z}\left(h_{g}, T, h h_{T}\right)
$$

Proof. Since $|\mathcal{G}|=1$, by the specification of the operation GCD and Notation $1,(i)$ holds. Therefore we have

$$
\begin{equation*}
\operatorname{Sat}(C)=\operatorname{Sat}\left(T_{<v}\right)=\operatorname{Sat}\left(T_{<v}^{\prime}\right) \tag{1}
\end{equation*}
$$

There exist polynomials $A$ and $B$ such that

$$
\begin{equation*}
g \equiv A p+B p^{\prime} \quad \bmod \quad \operatorname{Sat}(C) \tag{2}
\end{equation*}
$$

From (2), we have

$$
\begin{equation*}
\mathbf{V}(\operatorname{Sat}(C)) \subseteq \mathbf{V}\left(g-A p-B p^{\prime}\right) \tag{3}
\end{equation*}
$$

Therefore, we deduce

$$
\begin{aligned}
& \mathbf{W}(T) \bigcap \mathbf{W}\left(T^{\prime}\right) \\
& =\mathbf{W}\left(T_{<v} \cup p \cup T_{\geqslant v}\right) \bigcap \mathbf{W}\left(T_{<v}^{\prime} \cup p^{\prime} \cup T_{\geqslant v}^{\prime}\right) \\
& \subseteq\left(\mathbf{W}\left(T_{<v}\right) \cap \mathbf{V}(p)\right) \bigcap\left(\mathbf{W}\left(T_{<v}^{\prime}\right) \cap \mathbf{V}\left(p^{\prime}\right)\right) \\
& \subseteq \mathbf{V}\left(\operatorname{Sat}\left(T_{<v}\right)\right) \bigcap \mathbf{V}(p) \bigcap \mathbf{V}\left(p^{\prime}\right) \\
& \subseteq \mathbf{V}\left(g-A p-B p^{\prime}\right) \bigcap \mathbf{V}(p) \bigcap \mathbf{V}\left(p^{\prime}\right) \\
& \subseteq \mathbf{V}(g) .
\end{aligned}
$$

that is

$$
\begin{equation*}
\mathbf{W}(T) \bigcap \mathbf{W}\left(T^{\prime}\right) \subseteq \mathbf{V}(g) . \tag{4}
\end{equation*}
$$

Now we prove (ii). When $g \in \mathbb{K}, g \neq 0$, from (4) we deduce

$$
\begin{equation*}
\mathbf{W}(T) \bigcap \mathbf{W}\left(T^{\prime}\right)=\emptyset . \tag{5}
\end{equation*}
$$

Thus we have

$$
\begin{aligned}
& \mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right) \\
& =(\mathbf{W}(T) \backslash \mathbf{V}(h)) \backslash\left(\mathbf{W}\left(T^{\prime}\right) \backslash \mathbf{V}\left(h^{\prime}\right)\right) \\
& =(\mathbf{W}(T) \backslash \mathbf{V}(h)) \\
& =\mathbf{Z}(T, h)
\end{aligned}
$$

Now we prove (iii). Since $C=T_{<v}$ and $\operatorname{mvar}(g)$ is smaller than or equal to $v$, by the specification of GCD, $g$ is regular w.r.t $\operatorname{Sat}(T)$. We have following decompositions

$$
\begin{aligned}
\mathbf{Z}(T, h) & =\mathbf{Z}(T, g h) \bigsqcup \mathbf{Z}\left(g, T, h h_{T}\right) \\
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right) & =\mathbf{Z}\left(T^{\prime}, g h^{\prime}\right) \bigsqcup \mathbf{Z}\left(g, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
\end{aligned}
$$

On the other hand,

$$
\begin{aligned}
& \mathbf{Z}(T, g h) \bigcap \mathbf{Z}\left(T^{\prime}, g h^{\prime}\right) \\
& =\left(\mathbf{W}(T) \cap \mathbf{V}(g h)^{c}\right) \bigcap\left(\mathbf{W}\left(T^{\prime}\right) \cap \mathbf{V}\left(g h^{\prime}\right)^{c}\right) \\
& \subseteq\left(\mathbf{W}(T) \cap \mathbf{V}(g)^{c}\right) \bigcap\left(\mathbf{W}\left(T^{\prime}\right) \cap \mathbf{V}(g)^{c}\right) \\
& =\left(\mathbf{W}(T) \cap \mathbf{W}\left(T^{\prime}\right)\right) \bigcap \mathbf{V}(g)^{c} \\
& =\emptyset \quad \text { by (4). }
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& \mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right) \\
& =\left(\mathbf{Z}(T, g h) \backslash \mathbf{Z}\left(T^{\prime}, g h^{\prime}\right)\right) \bigsqcup\left(\mathbf{Z}\left(g, T, h h_{T}\right) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)\right) \\
& =\mathbf{Z}(T, g h) \bigsqcup\left(\mathbf{Z}\left(g, T, h h_{T}\right) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)\right) .
\end{aligned}
$$

Now we prove (iv.a). First, both $h^{\prime}$ and $h_{T}^{\prime}$ are regular w.r.t $\operatorname{Sat}(C)=\operatorname{Sat}\left(T_{<v}\right)=$ $\operatorname{Sat}\left(T_{<v}^{\prime}\right)$. From the construction of $D_{p}^{\prime}$, we have $h^{\prime} h_{T^{\prime}}$ is regular w.r.t $\operatorname{Sat}\left(D_{p}^{\prime}\right)$.

Assume that $\operatorname{mvar}(g)=v$ and $\operatorname{mdeg}(g)=\operatorname{mdeg}(p)$. We note that $\operatorname{mdeg}\left(p^{\prime}\right)>$ $\operatorname{mdeg}(p)$ holds. Otherwise we would have $\operatorname{mdeg}(g)=\operatorname{mdeg}(p)=\operatorname{mdeg}\left(p^{\prime}\right)$ which implies:

$$
\begin{equation*}
p \in \operatorname{Sat}\left(T_{\geqslant v}^{\prime}\right) \text { and } p^{\prime} \in \operatorname{Sat}\left(T_{\geqslant v}\right) . \tag{6}
\end{equation*}
$$

Thus

$$
\begin{array}{rlr}
\operatorname{Sat}\left(T_{\leqslant v}\right) & =\left\langle T_{\leqslant v}\right\rangle: h_{T \leqslant v}^{\infty}=\left\langle T_{<v} \cup p\right\rangle: h_{T \leqslant v}^{\infty} \\
& \subseteq \operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right): h_{T \leqslant v}^{\infty} \\
& =\operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right), & \text { by (6) }
\end{array}
$$

that is $\operatorname{Sat}\left(T_{\leqslant v}\right) \subseteq \operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right)$. Similarly, $\operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right) \subseteq \operatorname{Sat}\left(T_{\leqslant v}\right)$ holds. So we have $\operatorname{Sat}\left(T_{\leqslant v}^{\prime}\right)=\operatorname{Sat}\left(T_{\leqslant v}\right)$, a contradiction.

Hence, $\operatorname{mvar}\left(q^{\prime}\right)=v$.
By Lemma 6 [15], we know that $D_{p}^{\prime}$ and $D_{q^{\prime}}^{\prime}$ are regular chains. Then with Theorem 7 [15] and Lifting Theorem [15], we know

$$
\begin{aligned}
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right) & \subseteq \mathbf{Z}\left(D_{p}^{\prime}, h^{\prime}\right) \bigcup \mathbf{Z}\left(D_{q^{\prime}}^{\prime}, h^{\prime}\right) \bigcup \mathbf{Z}\left(h_{p}, T^{\prime}, h^{\prime}\right) \\
& \subseteq \overline{\mathbf{W}\left(T^{\prime}\right)} \backslash \mathbf{V}\left(h^{\prime}\right)
\end{aligned}
$$

By Lemma 2 we have

$$
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right) \bigcup \mathbf{Z}\left(D_{q^{\prime}}^{\prime}, h^{\prime} h_{T^{\prime}}\right) \bigcup \mathbf{Z}\left(h_{p}, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

Since

$$
\begin{aligned}
\mathbf{Z}\left(D_{q^{\prime}}^{\prime}, h^{\prime} h_{T^{\prime}}\right) & =\mathbf{Z}\left(D_{q^{\prime}}^{\prime}, h_{p} h^{\prime} h_{T^{\prime}}\right) \bigcup \mathbf{Z}\left(h_{p}, D_{q^{\prime}}^{\prime}, h^{\prime} h_{T}^{\prime}\right) \\
& =\mathbf{Z}\left(D_{q^{\prime}}^{\prime}, p h_{p} h^{\prime} h_{T^{\prime}}\right) \bigcup \mathbf{Z}\left(p, D_{q^{\prime}}^{\prime}, h_{p} h^{\prime} h_{T}^{\prime}\right) \bigcup \mathbf{Z}\left(h_{p}, D_{q^{\prime}}^{\prime}, h^{\prime} h_{T}^{\prime}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
& \mathbf{Z}\left(p, D_{q^{\prime}}^{\prime}, h_{p} h^{\prime} h_{T}^{\prime}\right) \subseteq \mathbf{Z}\left(D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right) \\
& \mathbf{Z}\left(h_{p}, D_{q^{\prime}}^{\prime}, h^{\prime} h_{T}^{\prime}\right) \subseteq \mathbf{Z}\left(h_{p}, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
\end{aligned}
$$

we deduce

$$
\mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right) \bigsqcup \mathbf{Z}\left(D_{q^{\prime}}^{\prime}, p h^{\prime} h_{T^{\prime}}\right) \bigsqcup \mathbf{Z}\left(h_{p}, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

Now observe that

$$
\begin{aligned}
& \mathbf{Z}(T, h) \bigcap \mathbf{Z}\left(D_{q^{\prime}}^{\prime}, p h^{\prime} h_{T^{\prime}}\right)=\emptyset, \text { and } \\
& \mathbf{Z}(T, h) \bigcap \mathbf{Z}\left(h_{p}, T^{\prime}, h^{\prime} h_{T^{\prime}}\right)=\emptyset .
\end{aligned}
$$

We obtain

$$
\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(D_{p}^{\prime}, h^{\prime} h_{T^{\prime}}\right)
$$

Finally we prove (iv.b). We assume that $\operatorname{mvar}(g)=v$ and $\operatorname{mdeg}(g)<\operatorname{mdeg}(p)$; this implies $\operatorname{mvar}(q)=v$. Applying Lemma 6 in [15] we know that $D_{g}$ and $D_{q}$ are regular chains and satisfy the desired rank condition. Then by Theorem 7 [15] and Lifting Theorem [15] we have

$$
\mathbf{Z}(T, h)=\mathbf{Z}\left(D_{g}, h h_{T}\right) \bigcup \mathbf{Z}\left(D_{q}, h h_{T}\right) \bigcup \mathbf{Z}\left(h_{g}, T, h h_{T}\right)
$$

This completes the whole proof.
Definition 7. Given two pairs of ranks $\left(\operatorname{rank}\left(T_{1}\right), \operatorname{rank}\left(T_{1}^{\prime}\right)\right)$ and $\left(\operatorname{rank}\left(T_{2}\right), \operatorname{rank}\left(T_{2}^{\prime}\right)\right)$, where $T_{1}, T_{2}, T_{1}^{\prime}, T_{2}^{\prime}$ are triangular sets. We define the product order $<_{p}$ of Ritt order $<_{r}$ on them as follows

$$
\begin{aligned}
& \left(\operatorname{rank}\left(T_{2}\right), \operatorname{rank}\left(T_{2}^{\prime}\right)\right)<_{p}\left(\operatorname{rank}\left(T_{1}\right), \operatorname{rank}\left(T_{1}^{\prime}\right)\right) \\
& \Longleftrightarrow\left\{\begin{array}{l}
\operatorname{rank}\left(T_{2}\right)<_{r} \operatorname{rank}\left(T_{1}\right) \text { or } \\
\operatorname{rank}\left(T_{2}\right)=\operatorname{rank}\left(T_{1}\right), \operatorname{rank}\left(T_{2}^{\prime}\right)<_{r} \operatorname{rank}\left(T_{1}^{\prime}\right)
\end{array}\right.
\end{aligned}
$$

In the following theorems, we prove the termination and correctness separately. Along with the proof of Theorem 2 we show the rank conditions are satisfied which is part of the correctness. The remained part, say zero set decomposition, will be proved in Theorem 3 .

Theorem 2. Algorithms Difference and DifferenceLR terminate and satisfy the rank conditions in their specifications.

Proof. The following two statements need to be proved
(i) Difference terminates with rank(Difference $\left.\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\right) \leqslant_{r} \operatorname{rank}([T, h])$,
(ii) DifferenceLR terminates with $\operatorname{rank}(\operatorname{DifferenceLR}(\mathcal{L}, \mathcal{R})) \leqslant_{r} \operatorname{rank}(\mathcal{L})$.

We prove them by induction on the product order $<_{p}$.
(1) Base case: there are no recursive calls to Difference or DifferenceLR. The termination of both algorithms is clear. By line 2,18 of the algorithm Difference, $\operatorname{rank}\left(\right.$ Difference $\left.\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\right) \leqslant_{r} \operatorname{rank}([T, h])$. By line 2,4 of the algorithm DifferenceLR, $\operatorname{rank}($ DifferenceLR $(\mathcal{L}, \mathcal{R})) \leqslant_{r} \operatorname{rank}(\mathcal{L})$.
(2) Induction hypothesis: assume that both $(i)$ and $(i i)$ hold with inputs whose ranks are smaller than the rank of $\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)$ w.r.t. $<_{p}$.
(3) $\mathrm{By}(1)$, if no recursive calls occur in one branch, then $(i)$ and $(i i)$ already hold. When recursive calls occur, by line $8,11,21,25,30,31,32,41,46$ and Lemma, 8, 9,10 we know the inputs of recursive calls to both Difference and DifferenceLR have smaller ranks than $\operatorname{rank}\left(\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\right)$ w.r.t $<_{p}$. By induction hypothesis, (i) holds. Finally, by line 8,15 of algorithm DifferenceLR and $(i),(i i)$ holds.

## Theorem 3. Both Difference and DifferenceLR satisfy their specifications.

Proof. By Theorem 2 Difference and DifferenceLR terminate and satisfy their rank conditions. So it suffices to prove the correctness of Difference and DifferenceLR, that is
(i) $\mathbf{Z}(T, h) \backslash \mathbf{Z}\left(T^{\prime}, h^{\prime}\right)=\mathbf{Z}\left(\right.$ Difference $\left.\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)\right)$,
(ii) $\mathbf{Z}(\mathcal{L}) \backslash \mathbf{Z}(\mathcal{R})=\mathbf{Z}($ DifferenceLR $(\mathcal{L}, \mathcal{R}))$.

We prove them by induction on the product order $<_{p}$.
(1) Base case: no recursive calls to Difference and DifferenceLR occur. First, by line 2, 18 of the algorithm Difference and Lemma6, 10 (i) holds. Second, by line 2,4 of the algorithm DifferenceLR, (ii) holds.
(2) Induction hypothesis: assume that both $(i)$ and $(i i)$ hold with inputs whose ranks are smaller than the rank of $\left([T, h],\left[T^{\prime}, h^{\prime}\right]\right)$ w.r.t. $<_{p}$.
(3) $\mathrm{By}(1)$, if no recursive calls occur, $(i)$ and (ii) already hold. When there are recursive calls, we first show ( $i$ ) holds. From the proof of Theorem2, in Difference, the inputs of recursive calls to Difference and DifferenceLR will have smaller ranks w.r.t. the product order $<_{p}$. Therefore, by (2), line $7,8,11,20,21,25,30$, 31, 32, 41, 46 and Lemma6, 8, 10, (i) holds.
Finally, by $(i)$ and line $5-18$ of algorithm DifferenceLR, (ii) holds.

## 4 Decomposition into Pairwise Disjoint Constructible Sets

We assume that Difference $\mathbf{L R}(\mathcal{L}, \mathcal{R})$ returns a list of regular systems sorted by increasing rank.

Definition 8. Let $\mathcal{S}$ be a list of regular systems sorted by increasing rank. If $\mathcal{S}$ is empty or consists of a single regular system $[T, h]$, define $\operatorname{MPD}(\mathcal{S})=\mathcal{S}$. Otherwise, let $\mathcal{S}=\mathcal{L}+\mathcal{R}$, where $|\mathcal{L}|=|\mathcal{R}|$ or $|\mathcal{L}|=|\mathcal{R}|+1$ (and + denotes concatenation of lists). Define

$$
\operatorname{MPD}(\mathcal{S})=\operatorname{MPD}(\text { DifferenceLR }(\mathcal{L}, \mathcal{R}))+\operatorname{MPD}(\mathcal{R})
$$

Definition 9. For a regular system $S=[T, h]$, let $\mathbf{Z}_{0}(S)$ denote the zero set of $S$ considered as a regular system in $\hat{\mathbb{K}}[\operatorname{mvar}(T)]:=\overline{\mathbb{K}(Y \backslash \operatorname{mvar}(T))}[\operatorname{mvar}(T)]$.

Lemma 11. For every regular system $S, \mathbf{Z}_{0}(S)$ is non-empty and finite.
Proof. If the regular system $S=[T, h]$ is considered in $\hat{\mathbb{K}}[\operatorname{mvar}(T)]$, it remains to be a regular system and, moreover, $T$ becomes a zero-dimensional regular chain. We have therefore

$$
\mathbf{Z}_{0}(S)=\mathbf{W}_{\hat{\mathbb{K}}}(T) \backslash \mathbf{V}_{\hat{\mathbb{K}}}(h)=\mathbf{V}_{\hat{\mathbb{K}}}(T)
$$

Definition 10. For a finite set of regular systems $\mathcal{S}=\left\{\left[T_{1}, h_{1}\right], \ldots,\left[T_{k}, h_{k}\right]\right\}$ such that $\operatorname{rank}\left(T_{1}\right)=\cdots=\operatorname{rank}\left(T_{k}\right)$, define

$$
\mathbf{Z}_{0}(\mathcal{S})=\mathbf{Z}_{0}\left(\left[T_{1}, h_{1}\right]\right) \cup \ldots \cup \mathbf{Z}_{0}\left(\left[T_{k}, h_{k}\right]\right)
$$

For an arbitrary finite set of regular systems $\mathcal{S}$, let $\mathcal{S}_{\operatorname{rank}(\mathcal{S})}$ denote the subset of regular systems of maximal rank. Define $\mathbf{Z}_{0}(\mathcal{S})=\mathbf{Z}_{0}\left(\mathcal{S}_{\operatorname{rank}}(\mathcal{S})\right.$.

Lemma 12. Let $\mathcal{S}$ be a list of regular systems sorted by increasing rank represented as a concatenation of two non-empty sublists: $\mathcal{S}=\mathcal{L}+\mathcal{R}$. Let $\mathcal{C}=\operatorname{DifferenceLR}(\mathcal{L}, \mathcal{R})$. Then either $\operatorname{rank}(\mathcal{C})<\operatorname{rank}(\mathcal{S})$, or $\left|\mathbf{Z}_{0}(\mathcal{C})\right|<\left|\mathbf{Z}_{0}(\mathcal{S})\right|$.

Proof. If $\operatorname{rank}(\mathcal{L})<\operatorname{rank}(\mathcal{S})$, then $\operatorname{rank}(\mathcal{C})<\operatorname{rank}(\mathcal{S})$ by Theorem 2 Otherwise, $\operatorname{rank}(\mathcal{L})=\operatorname{rank}(\mathcal{S})$ and, since $\mathcal{S}$ is sorted by increasing rank, the rank of every system in $\mathcal{R}$ equals $\operatorname{rank}(\mathcal{S})$. By Theorem 2 we have $\operatorname{rank}(\mathcal{C}) \leq \operatorname{rank}(\mathcal{S})$. In case of strict inequality we are done, so assume that $\operatorname{rank}(\mathcal{C})=\operatorname{rank}(\mathcal{S})$.

Denote $r=\operatorname{rank}(\mathcal{L})=\operatorname{rank}(\mathcal{C})=\operatorname{rank}(\mathcal{R})=\operatorname{rank}(\mathcal{S})$. We have:

$$
\bigcup_{C \in \mathcal{C}_{r}} \mathbf{Z}(C) \subseteq \bigcup_{A \in \mathcal{L}_{r}} \mathbf{Z}(A) \backslash \bigcup_{B \in \mathcal{R}} \mathbf{Z}(B)
$$

which implies

$$
\mathbf{Z}_{0}(\mathcal{C}) \subseteq \mathbf{Z}_{0}(\mathcal{L}) \backslash \bigcup_{B \in \mathcal{R}} \mathbf{Z}_{0}(B)
$$

Since, by Lemma $11 \mathbf{Z}_{0}(\mathcal{S})=\mathbf{Z}_{0}(\mathcal{L}) \cup \mathbf{Z}_{0}(\mathcal{R})$ is finite and $\bigcup_{B \in \mathcal{R}} \mathbf{Z}(B) \neq \varnothing$, we obtain the desired $\left|\mathbf{Z}_{0}(\mathcal{C})\right|<\left|\mathbf{Z}_{0}(\mathcal{S})\right|$.

Lemma 13. For any list $\mathcal{S}$ of regular systems, $\mathcal{D}=\operatorname{MPD}(\mathcal{S})$ is well-defined.
Proof. We define a well-order on the set of all sorted finite lists of regular systems and prove the statement by induction on this well-order.

For a non-empty list $\mathcal{S}$, let $\phi(\mathcal{S})=\left(\operatorname{rank}(\mathcal{S}), \mathbf{Z}_{0}(\mathcal{S}),|\mathcal{S}|\right)$. Let $\mathcal{L} \prec \mathcal{R}$ iff $\phi(\mathcal{L})<_{\text {lex }}$ $\phi(\mathcal{R})$. Since $<_{\text {lex }}$ is the lexicographic product of three well-orders, $<_{\text {lex }}$ is a well-order, whence so is $\prec$. Define the empty list to be less than any non-empty list w.r.t. $\prec$.

For empty and singleton lists $\mathcal{S}, \operatorname{MPD}(\mathcal{S})$ is well-defined. Let $\mathcal{S}$ be a non-singleton and non-empty list. Assume that $\operatorname{MPD}\left(\mathcal{S}^{\prime}\right)$ is defined for all lists $\mathcal{S}^{\prime}$ such that $\mathcal{S}^{\prime} \prec \mathcal{S}$. Let, as in Definition $8 \mathcal{S}=\mathcal{L}+\mathcal{R}$, where $|\mathcal{L}|=|\mathcal{R}|$ or $|\mathcal{L}|=|\mathcal{R}|+1$. Then by

Lemma 12, Difference $(\mathcal{L}, \mathcal{R}) \prec \mathcal{S}$. Also, $\operatorname{rank}(\mathcal{R}) \leq \operatorname{rank}(\mathcal{S}), \mathbf{Z}_{0}(\mathcal{R}) \leq \mathbf{Z}_{0}(\mathcal{S})$, and $|\mathcal{R}|<|\mathcal{S}|$, whence $\mathcal{R} \prec \mathcal{S}$. This implies that $\operatorname{MPD}(\mathcal{S})$ is well-defined according to Definition 8

Note that Definition 8 yields a recursive algorithm for computing $\operatorname{MPD}(\mathcal{S})$, which terminates according to the previous lemma. The output of this algorithm is a decomposition of the union of zero-sets of regular systems in $\mathcal{S}$ into a disjoint union of zero-sets of regular systems:

Proposition 2. For all distinct regular systems $R, S \in \mathcal{D}=\operatorname{MPD}(\mathcal{S})$, we have $\mathbf{Z}(R) \cap \mathbf{Z}(S)=\varnothing$, and

$$
\bigcup_{R \in \mathcal{S}} \mathbf{Z}(S)=\bigcup_{S \in \mathcal{D}} \mathbf{Z}(D)
$$

Proof. Follows immediately from the definition of MPD.
In the following section, to compute comprehensive triangular decompositions, we will see that SMPD (strongly make pairwise disjoint) is really required. Given a set of regular systems $A_{1}, \cdots, A_{s}$, SMPD compute another set of regular systems $B_{1}, \cdots, B_{t}$ whose zero sets are pairwise disjoint, such that each $\mathbf{Z}\left(A_{i}\right)$ writes as a union of some of the $\mathbf{Z}\left(B_{1}\right), \cdots, \mathbf{Z}\left(B_{t}\right)$.

```
Algorithm 3. SMPD \((\mathcal{S})\)
    if \(|\mathcal{S}| \leq 1\) then
        output \(\mathcal{S}\)
    end if
    Let \(\left[T_{0}, h_{0}\right] \in \mathcal{S}, \mathcal{S} \leftarrow \mathcal{S} \backslash\left\{\left[T_{0}, h_{0}\right]\right\}\)
    \(\mathcal{S} \leftarrow \operatorname{SMPD}(\mathcal{S})\)
    for \([T, h] \in \mathcal{S}\) do
        \(\mathcal{A} \leftarrow\) Difference \(\left([T, h],\left[T_{0}, h_{0}\right]\right)\)
        \(\mathcal{B} \leftarrow \operatorname{DifferenceLR}([T, h], \mathcal{A})\)
        output MPD \((\mathcal{A})\)
        output MPD \((\mathcal{B})\)
    end for
    \(\mathcal{C} \leftarrow \operatorname{DifferenceLR}\left(\left[T_{0}, h_{0}\right], \mathcal{S}\right)\)
    output MPD (C)
```

Proposition 3. The Algorithm SMPD terminates and is correct.
PROOF. It follows directly from the termination and correctness of algorithms Difference, DifferenceLR and MPD.

## 5 Comprehensive Triangular Decomposition

In this section we introduce the concept of comprehensive triangular decomposition of an algebraic variety. We propose an algorithm for computing this decomposition and apply it to compute the set of all parameter values at which a given parametric system has an empty or an infinite set of solutions.

Notation 2. From now on, we assume that $n=m+d$, the variables $Y_{1}, \ldots, Y_{d}$ are renamed $U_{1}, \ldots, U_{d}$ and viewed as parameters, whereas $Y_{d+1}, \ldots, Y_{n}$ are renamed $X_{1}, \ldots, X_{m}$ and regarded as unknowns.

If the polynomial set $F \subset \mathbb{K}[Y]$ involves polynomials from $\mathbb{K}[U]$ only, we denote by $\mathbf{V}^{U}(F)$ its variety in $\overline{\mathbb{K}}^{d}$. Similarly, if the regular chain $T \subset \mathbb{K}[Y]$ involves polynomials from $\mathbb{K}[U]$ only, we denote by $\mathbf{W}^{U}(T)$ its quasi-component in $\overline{\mathbb{K}}^{d}$.

Notation 3. Let $p \in \mathbb{K}[U][X]$ be a polynomial. We denote by $\mathbf{V}^{U}(p)$ the variety of $\overline{\mathbb{K}}^{d}$, consisting of the common roots of the coefficients of $p$, when $p$ is regarded as $a$ polynomial with variables in $X$ and coefficients in $\mathbb{K}[U]$. Then, we define $\mathbf{V}^{U}(F)$ as the intersection of all $\mathbf{V}^{U}(p)$ for $p \in F$.

For $u \in \overline{\mathbb{K}}^{d}$, we denote by $p(u)$ the polynomial of $\overline{\mathbb{K}}[X]$ obtained by evaluating $p$ at $U_{1}=u_{1}, \ldots, U_{d}=u_{d}$. Clearly, for all $u \in \overline{\mathbb{K}}^{d}$, the polynomial $p(u)$ is identically null iff $u \in \mathbf{V}^{U}(p)$. Then, we denote by $F(u)$ the set of all non-zero $p(u)$ for $p \in F$.

Definition 11. Let $T \subset \mathbb{K}[U, X]$ be a regular chain. The defining set of $T$ w.r.t. $U$, denoted by $\mathbf{D}^{U}(T)$, is the constructible set of $\overline{\mathbb{K}}^{d}$ given by

$$
\mathbf{D}^{U}(T)=\mathbf{W}^{U}(T \cap \mathbb{K}[U]) \backslash \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T_{>U_{d}}}, T_{>U_{d}}\right)\right)
$$

Let $u \in \mathbf{W}^{U}(T \cap \mathbb{K}[U])$. We say that the regular chain $T$ specializes well at $u$ if $T(u)$ is a regular chain in $\overline{\mathbb{K}}[X]$ such that $\operatorname{rank}(T(u))=\operatorname{rank}\left(T_{>U_{d}}\right)$.
Remark 2. Since $\mathbf{D}^{U}(T)$ is a constructible set, by Lemma 5 there exists an algorithm to compute a set of regular systems $\mathcal{R}^{U}(T)$, such that $\mathbf{D}^{U}(T)=\mathbf{Z}\left(\mathcal{R}^{U}(T)\right)$.
Lemma 14. Let $T \subset \mathbb{K}[U, X]$ be a regular chain with $\operatorname{mvar}(T) \subseteq X$ and let $u \in \overline{\mathbb{K}}^{d}$. We have

$$
u \notin \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T}, T\right)\right) \Longleftrightarrow \operatorname{res}\left(h_{T(u)}, T(u)\right) \neq 0 \text { and } h_{T}(u) \neq 0
$$

Proof. " $\Leftarrow$ " If $h_{T}(u) \neq 0$ and $\operatorname{res}\left(h_{T(u)}, T(u)\right) \neq 0$, then

$$
\operatorname{res}\left(h_{T(u)}, T(u)\right)=\operatorname{res}\left(h_{T}(u), T(u)\right) \neq 0
$$

which implies res $\left(h_{T}, T\right)(u) \neq 0$. So $u \notin \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T}, T\right)\right)$.
" $\Rightarrow$ " We prove this by induction on $|T|$.
If $|T|=1$, then $u \notin \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T}, T\right)\right)$ implies $h_{T}(u) \neq 0$ and therefore

$$
\operatorname{res}\left(h_{T(u)}, T(u)\right)=h_{T(u)}=h_{T}(u) \neq 0
$$

Now we assume that the conclusion holds for $|T|=n-1$. If $|T|=n$, let $v$ be the largest variable in $\operatorname{mvar}(T)$. Since $u \notin \mathbf{V}^{U}\left(\operatorname{res}\left(h_{T}, T\right)\right)$, we have

$$
\operatorname{res}\left(h_{T}, T\right)(u)=\operatorname{res}\left(h_{T}, T_{<v}\right)(u) \neq 0
$$

Therefore, $\operatorname{res}\left(h_{T_{<v}}, T_{<v}\right)(u) \neq 0$. By induction hypothesis, we know $h_{T_{<v}}(u) \neq$ 0 . By the specialization property of resultant, $\operatorname{res}\left(h_{T}(u), T_{<v}(u)\right) \neq 0$ and therefore $h_{T}(u) \neq 0$. So res $\left(h_{T}, T\right)(u) \neq 0$ implies $\operatorname{res}\left(h_{T(u)}, T(u)\right) \neq 0$.

Proposition 4. Let $T \subset \mathbb{K}[U, X]$ be a regular chain and let $u \in \mathbf{W}^{U}(T \cap \mathbb{K}[U])$. The regular chain $T$ specializes well at $u \in \overline{\mathbb{K}}^{d}$ if and only if $u \in \mathbf{D}^{U}(T)$.

Proof. Assume that $u \in \mathbf{D}^{U}(T)$. We prove that $T$ specializes well at $u$. From Lemma 14 we have

$$
\operatorname{res}\left(h_{T_{>U_{d}}(u)}, T_{>U_{d}}(u)\right) \neq 0 \text { and } h_{T_{>U_{d}}}(u) \neq 0
$$

With $u \in \mathbf{W}^{U}(T \cap \mathbb{K}[U])$, which implies $(T \cap \mathbb{K}[U])(u)=\{0\}$, we conclude that $\operatorname{rank}(T(u))=\operatorname{rank}\left(T_{>U_{d}}\right)$. Moreover, by Theorem $1 T(u)$ is a regular chain. Therefore, the regular chain $T$ specializes well at $u$. The converse implication is proved similarly.

Definition 12. Let $T \subset \mathbb{K}[U, X]$ be a regular chain. The comprehensive quasi-component of $T$ w.r.t. $U$, denoted by $\mathbf{W}_{C}(T)$, is defined by

$$
\mathbf{W}_{C}(T)=\mathbf{W}(T) \cap \Pi_{U}^{-1}\left(\mathbf{D}^{U}(T)\right) .
$$

Proposition 5. Let $T \subset \mathbb{K}[U, X]$ be a regular chain. The following properties hold:
(1) We have: $\mathbf{W}_{C}(T)=\mathbf{W}(T) \backslash \Pi_{U}^{-1}\left(\mathbf{V}^{U}\left(\operatorname{res}\left(h_{T>U_{d}}, T_{>U_{d}}\right)\right)\right)$.
(2) We have: $\Pi_{U}\left(\mathbf{W}_{C}(T)\right)=\mathbf{D}^{U}(T)$.

Proof. It follows from Definition 11 and Lemma 14
Definition 13. Let $F \subset \mathbb{K}[U, X]$ be a finite polynomial set. A comprehensive triangular decomposition of $\mathbf{V}(F)$ is given by :

1. a finite partition $\mathcal{C}$ of $\Pi_{U}(\mathbf{V}(F))$,
2. for each $C \in \mathcal{C}$ a set of regular chains $\mathcal{T}_{C}$ of $\mathbb{K}[U, X]$ such that for $u \in C$ each of the regular chains $T \in \mathcal{T}_{C}$ specializes well at $u$ and we have for all $u \in C$

$$
\mathbf{V}(F(u))=\bigcup_{T \in \mathcal{T}_{C}} \mathbf{W}(T(u))
$$

We will compute the above comprehensive triangular decomposition with the help of the following auxiliary concept:

Definition 14. Let $F \subset \mathbb{K}[U, X]$ be a finite polynomial set. A pre-comprehensive triangular decomposition (PCTD) of $\mathbf{V}(F)$ is a family of regular chains $\mathcal{T}$ satisfying the following property: for each $u \in \overline{\mathbb{K}}^{d}$, let $\mathcal{T}_{u}$ be the subfamily of all regular chains in $\mathcal{T}$ that specialize well at $u$; then

$$
\mathbf{V}(F(u))=\bigcup_{T \in \mathcal{T}_{u}} \mathbf{W}(T(u))
$$

Proposition 6. Let $F \subset \mathbb{K}[U, X]$ be a finite polynomial set. A triangular decomposition $\mathcal{T}$ of $\mathbf{V}(F)$ is a pre-comprehensive triangular decomposition if and only if

$$
\mathbf{V}(F)=\bigcup_{T \in \mathcal{T}} W_{C}(T)
$$

Proof. It follows from the definition of $W_{C}(T)$, Proposition 4 and the definition of pre-comprehensive triangular decomposition.

```
Algorithm 4. PCTD \((F)\)
Input: A finite set \(F \subset \mathbb{K}[U, X]\).
Output: A PCTD of \(\mathbf{V}(F)\).
    \(\mathcal{T} \leftarrow\) Triangularize \((F)\)
    while \(\mathcal{T} \neq \emptyset\) do
        let \(T \in \mathcal{T}, \mathcal{T} \leftarrow \mathcal{T} \backslash\{T\}\)
        output \(T\)
        \(G \leftarrow \operatorname{COEFFICIENTS}\left(\operatorname{res}\left(h_{T_{>U_{d}}}, T_{>U_{d}}\right), U\right)\)
        \(\mathcal{T} \leftarrow \mathcal{T} \cup \operatorname{Triangularize}(G, T)\)
    end while
```

Proposition 7. Algorithm 4 computes a pre-comprehensive triangular decomposition of $\mathbf{V}(F)$.

Proof. The loop satisfies the following invariant: the union of all $\mathbf{W}(T)$, where $T$ ranges over $\mathcal{T}$, and of the $\mathbf{W}\left(T^{\prime}\right)$, where $T^{\prime}$ ranges over the current output, equals $\mathbf{V}(F)$. Indeed, the invariant holds at the beginning, when the output is empty; and for the regular chain $T$ taken from $\mathcal{T}$ at the current iteration, we have $\mathbf{W}(T) \backslash \mathbf{W}_{C}(T)=$ $\mathbf{V}(G) \cap \mathbf{W}(T)$ by Proposition 5(1). Then, correctness of the algorithm follows from Proposition6 and the fact that at the end $\mathcal{T}=\varnothing$.

Since polynomials in $G$ do not involve the main variables of $T$, by Lemma 3 they are regular w.r.t $\operatorname{Sat}(T)$. Then by Lemma 1 either the output of Triangularize $(G, T)$ is empty or the dimensions of the regular chains computed by Triangularize $(G, T)$ are strictly less than that of $T$. Therefore, the algorithm terminates.

Proposition 8. Algorithm 5 computes a comprehensive triangular decomposition of $F \subset \mathbb{K}[U, X]$.

Proof. Let $\mathcal{T}$ be the output of $\operatorname{PCTD}(F)$. By Proposition 6 and Proposition 5 (2), we have

$$
\Pi_{U}(\mathbf{V}(F))=\bigcup_{T \in \mathcal{T}} \mathbf{D}^{U}(T)
$$

Then the conclusion follows from the definition of comprehensive triangular decomposition, Proposition 3,7 and Remark 2
Given a polynomial set $F \subset \mathbb{K}[U, X]$, a natural question is to describe the points $u$ of $\overline{\mathbb{K}}^{d}$ for which the specialized system $F(u)$ admits a finite and positive number of solutions in $\overline{\mathbb{K}}^{m}$. This question is formalized by the following definition.

Definition 15. The discriminant set of $F$ is defined as the set of all points $u \in \overline{\mathbb{K}}^{d}$ for which $\mathbf{V}(F(u))$ is empty or infinite.

```
Algorithm 5. CTD \((F)\)
Input: A finite set \(F \subset \mathbb{K}[U, X]\).
Output: A CTD of \(\mathbf{V}(F)\).
    \(\mathcal{T} \leftarrow \mathbf{P C T D}(F)\)
    \(\mathcal{S} \leftarrow \emptyset\)
    for \(T \in \mathcal{T}\) do
        \(\mathcal{S} \leftarrow \mathcal{S} \cup \mathcal{R}^{U}(T)\)
    end for
    \(\mathcal{S} \leftarrow \operatorname{SMPD}(\mathcal{S})\)
    while \(\mathcal{S} \neq \emptyset\) do
        let \(C \in \mathcal{S}, \mathcal{S} \leftarrow \mathcal{S} \backslash C\)
        \(\mathcal{T}_{C} \leftarrow\) regular chains in \(\mathcal{T}\) associated to \(C\)
        output \(\left(C, \mathcal{T}_{C}\right)\)
    end while
```

Theorem 4. If $\mathcal{T}$ is a pre-comprehensive triangular decomposition of $\mathbf{V}(F)$, then the following is the discriminant set of $F$ :

$$
\left(\bigcup_{\substack{T \in \mathcal{T} \\ X \in \operatorname{mvar}(T)}} \mathbf{D}^{U}(T)\right) \cup\left(\bigcap_{\substack{T \in \mathcal{T} \\ X \subseteq \operatorname{mvar}(T)}} \overline{\mathbb{K}}^{d} \backslash \mathbf{D}^{U}(T)\right)
$$

Proof. By Proposition 4 for every parameter value $u \in \overline{\mathbb{K}}^{d}$, the set $\{T(u) \mid T \in$ $\mathcal{T}$ and $\left.u \in \mathbf{D}^{U}(T)\right\}$ is a triangular decomposition of $\mathbf{V}(F(u))$ into regular chains. In particular, if there exists no $T \in \mathcal{T}$ such that $u \in \mathbf{D}^{U}(T)$ holds, then $\mathbf{V}(F(u))=\emptyset$.

Therefore, $u$ yields finitely many solutions (and at least one) if and only if the following conditions hold:

- $u$ belongs to at least one $\mathbf{D}^{U}(T)$ such that $X \subseteq \operatorname{mvar}(T)$, i.e., $T(u)$ is a zerodimensional regular chain.
- $u$ does not belong to any $\mathbf{D}^{U}(T)$ such that $X \nsubseteq \operatorname{mvar}(T)$, i.e., $T(u)$ is a positivedimensional regular chain.

Remark 3. By Theorem 4 and Proposition 8 we have completely answered the two problems proposed in the introduction.

## 6 Implementation

We have implemented the algorithm for computing comprehensive triangular decompositions (CTD) based on RegularChains library in Maple 11. Our main function CTD calls essentially three functions

- Triangularize, computing a triangular decomposition of the input system $F$,
- PCTD, deducing a pre-comprehensive triangular decomposition of $F$,
- SMPD, obtaining a comprehensive triangular decomposition of $F$.

Table 1. Solving timings and number of cells of CTD

| Sys | Name | Triangularize | PCTD | SMPD | CTD | \#Cells |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | MontesS1 | 0.089 | 0.002 | 0.031 | 0.122 | 3 |
| 2 | MontesS2 | 0.031 | 0.002 | 0 | 0.033 | 1 |
| 3 | MontesS3 | 0.103 | 0.006 | 0.005 | 0.114 | 2 |
| 4 | MontesS4 | 0.101 | 0.016 | 0 | 0.117 | 1 |
| 5 | MontesS5 | 0.383 | 0.022 | 0.465 | 0.870 | 11 |
| 6 | MontesS6 | 0.395 | 0.019 | 0.121 | 0.535 | 4 |
| 7 | MontesS7 | 0.416 | 0.215 | 0.108 | 0.739 | 4 |
| 8 | MontesS8 | 0.729 | 0.001 | 0.016 | 0.746 | 2 |
| 9 | MontesS9 | 0.945 | 0.116 | 3.817 | 4.878 | 23 |
| 10 | MontesS10 | 5.325 | 0.684 | 1.138 | 7.147 | 10 |
| 11 | MontesS11 | 0.757 | 0.208 | 12.302 | 13.267 | 28 |
| 12 | MonteSS12 | 14.199 | 2.419 | 10.114 | 26.732 | 10 |
| 13 | MontesS13 | 0.415 | 0.143 | 1.268 | 1.826 | 9 |
| 14 | MontesS14 | 41.167 | 31.510 | 0.303 | 72.980 | 4 |
| 15 | MontesS15 | 6.919 | 0.579 | 1.123 | 8.621 | 5 |
| 16 | MontesS16 | 6.963 | 0.083 | 2.407 | 9.453 | 21 |
| 17 | AlkashiSinus | 0.716 | 0.191 | 0.574 | 1.481 | 6 |
| 18 | Bronstein | 2.526 | 0.017 | 0.548 | 3.091 | 6 |
| 19 | Gerdt | 3.863 | 0.006 | 0.733 | 4.602 | 5 |
| 20 | Hereman-2 | 1.826 | 0.019 | 0.020 | 1.865 | 2 |
| 21 | Lanconelli | 2.056 | 0.336 | 3.430 | 5.822 | 14 |
| 22 | genLinSyst-3-2 | 1.624 | 0.275 | 25.413 | 27.312 | 32 |
| 23 | genLinSyst-3-3 | 9.571 | 1.824 | 1097.291 | 1108.686 | 116 |
| 24 | Wang93 | 6.795 | 37.232 | 11.828 | 55.855 | 8 |
| 25 | Maclane | 12.955 | 0.403 | 54.197 | 67.555 | 21 |
| 26 | Neural | 15.279 | 19.313 | 0.530 | 35.122 | 4 |
| 27 | Leykin-1 | 1261.751 | 86.460 | 27.180 | 1375.391 | 57 |
| 28 | Lazard-ascm2001 | 60.698 | 2817.801 | - | - | - |
| 29 | Pavelle | - | - | - | - | - |
| 30 | Cheaters-homotopy | - | - | - | - | - |

We provide comparative benchmarks with MAPLE implementations of related methods for solving parametric polynomial systems, namely: decomposition into regular systems by Wang [19] and discussing parametric Gröbner bases by Montes [14]. Corresponding MAPLE functions are RegSer and DISPGB, respectively.

Note that the specifications of these three methods are different. The outputs of CTD and DISPGB depend on the choice of the parameter sets, whereas RegSer does not require to specify parameters. RegSer decomposes the input system into pairwise disjoint constructible sets given by regular systems. CTD computes a comprehensive triangular decomposition, and thus a family of triangular decompositions with a partition of the parameter space. DISPGB computes a family of comprehensive Gröbner bases with a partition of the parameter space.

We run CTD in Maple 11 using an Intel Pentium 4 processor (3.20GHz CPU, 2.0GB total memory, and Red Hat 4.0.0-9); we set the time-out to 1 hour. Due to the current availability of RegSer and DISPGB, the timings obtained by these two functions are

Table 2. Solving timings and number of components/cells in three algorithms

|  | DISPGB |  | RegSer |  | CTD |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Sys | Time (s) | \# Cells | Time (s) | \# Components | Time (s) | \# Cells |
| 1 | 0.509 | 2 | 0.021 | 3 | 0.122 | 3 |
| 2 | 0.410 | 2 | 0.021 | 1 | 0.033 | 1 |
| 3 | 0.550 | 2 | 0.060 | 3 | 0.114 | 2 |
| 4 | 1.511 | 2 | 0.070 | 1 | 0.117 | 1 |
| 5 | 1.030 | 3 | 0.099 | 4 | 0.870 | 11 |
| 6 | 1.350 | 4 | 0.049 | 5 | 0.535 | 4 |
| 7 | 1.609 | 2 | 0.180 | 4 | 0.739 | 4 |
| 8 | 2.181 | 3 | 0.150 | 4 | 0.746 | 2 |
| 9 | 10.710 | 5 | 0.171 | 7 | 4.878 | 23 |
| 10 | 9.659 | 5 | 0.329 | 5 | 7.147 | 10 |
| 11 | 0.489 | 3 | 0.260 | 9 | 13.267 | 28 |
| 12 | 259.730 | 5 | 2.381 | 23 | 26.732 | 10 |
| 13 | 5.830 | 9 | 0.199 | 9 | 1.826 | 9 |
| 14 | - | - | - | - | 72.980 | 4 |
| 15 | 30.470 | 7 | 0.640 | 10 | 8.621 | 5 |
| 16 | 61.831 | 7 | 6.060 | 22 | 9.453 | 21 |
| 17 | 4.619 | 6 | 0.150 | 5 | 1.481 | 6 |
| 18 | 8.791 | 5 | 0.319 | 6 | 3.091 | 6 |
| 19 | 20.739 | 5 | 3.019 | 10 | 4.602 | 5 |
| 20 | 101.251 | 2 | 0.371 | 7 | 1.865 | 2 |
| 21 | 43.441 | 4 | 0.330 | 7 | 5.822 | 14 |
| 22 | - | - | 0.350 | 18 | 27.312 | 32 |
| 23 | - | - | 2.031 | 61 | 1108.686 | 116 |
| 24 | - | - | 4.040 | 6 | 55.855 | 8 |
| 25 | 83.210 | 11 | - | - | 67.555 | 21 |
| 26 | - | - | - | - | 35.122 | 4 |
| 27 | - | - | - | - | 1375.391 | 57 |
| 28 | - | - | - | - | - | - |
| 29 | - | - | - | - | - | - |
| 30 | - | - | - | - | - | - |

performed in Maple 8 on Intel Pentium 4 machines $(1.60 \mathrm{GHz}$ CPU, 513 MB memory and Red Hat Linux 3.2.2-5); and the time-out is 2 hours. The 30 test-systems used in our experimentation are chosen from [13|18|21].

As shown in the above two tables, our implementation of the CTD algorithm can solve all problems which can be solved by the other methods. In addition, the CTD can solve 4 test-systems which are out of reach of the other two methods, generally due to memory consumption.

## 7 Conclusion

Comprehensive triangular decomposition is a powerful tool for the analysis of parametric polynomial systems: its purpose is to partition the parameter space into regions, so
that within each region the "geometry" of the algebraic variety of the specialized system is the same for all values of the parameters.

As the main technical tool, we proposed an algorithm that represents the difference of two constructible sets as finite unions of regular systems. From there, we have deduced an algorithmic solution for a set theoretical instance of the coprime factorization problem: refining a family of constructible sets into a family of pairwise disjoint constructible sets.

We have reported on an implementation of our algorithm computing CTDs, based on the RegularChains library in Maple. Our comparative benchmarks, with Maple implementations of related methods for solving parametric polynomial systems, illustrate the good performances of our CTD code.

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