

A Modular Algorithm for Computing the Characteristic Polynomial of an Integer Matrix in Maple.

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Introduction

Let A be an $n \times n$ matrix of integers. In this paper we present details of our Maple implementation of a modular method for computing $c(x)$, the characteristic polynomial of A . Our implementation considers several different representations for the primes, including the use of double precision floats. The algorithm presently implemented in Maple releases 7–9 is the Berkowitz algorithm [2, 1]. We present some timings comparing the two methods on a 364×364 matrix arising from an application in combinatorics from Quaintance [6].

One way to compute the characteristic polynomial of A is to evaluate the characteristic matrix at n points, compute n determinants of integer matrices, then interpolate to obtain the characteristic polynomial. The determinants of the integer matrices can be computed using a fraction-free Gaussian elimination algorithm (see Chapter 9 of Geddes et. al [4]) in $O(n^3)$ integer multiplications and divisions. This approach will lead to an algorithm that requires $O(n^4)$ integer operations.

Another algorithm is the “Berkowitz” algorithm [2]. It is a division free algorithm and thus can be used to compute the characteristic polynomial of a matrix over any commutative ring R . It does $O(n^4)$ multiplications in R . In [1], Abdeljaoued described a Maple implementation of a sequential version of the Berkowitz algorithm and compared it with the interpolation method and other methods. His implementation improves with sparsity to $O(n^3)$ multiplications when the matrix has $O(n)$ non-zero entries.

A Modular Algorithm

The modular algorithm we have implemented computes the characteristic polynomial of A modulo a sequence of machine primes p_1, p_2, \dots and applies the Chinese remainder theorem to reconstruct the coefficients of the characteristic polynomial. For each prime p it computes the characteristic polynomial modulo p via the Hessenberg matrix in $O(n^3)$ arithmetic operations in \mathbb{Z}_p . The algorithm is described in Chapter 2 of Cohen’s book. See [3].

Consider a sequence of k machine primes p_1, p_2, \dots, p_k , where $2 < p_i < B$. B should be chosen small enough such that B^2 fits into a single register, so arithmetic operations in \mathbb{Z}_p can be done directly by the hardware, but also large enough so that we don’t require too many primes. Therefore, we let $B = \lfloor \sqrt{2^{31} - 1} \rfloor$ for 32-bit integers, $B = \lfloor \sqrt{2^{63} - 1} \rfloor$ for 64-bit integers, and $B = \lfloor \sqrt{2^{52} - 1} \rfloor$ for 64-bit floating point representations.

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Algorithm:

1. Compute a bound M for the size of coefficients of $c(x)$.
2. Choose k machine primes $p_1, p_2, \dots, p_k < B$ such that $\prod_{i=1}^k p_i > 2M$.
3. **for** $i = 1$ to k **do**
 - (a) $A_i \leftarrow A \bmod p_i$.
 - (b) Compute $c_i(x)$ — the characteristic polynomial of A_i over \mathbb{Z}_{p_i} .
4. Apply the Chinese remainder theorem to reconstruct $c(x)$ from the $c_i(x)$'s.

Implementation Details and Timings

In order to improve the running time of our algorithm, we've implemented the Hessenberg algorithm over \mathbb{Z}_{p_i} in the C programming language and the rest of the algorithm in Maple. We used the Maple foreign function interface to call the C code. See [5]. We've implemented both the 32-bit integer version and 64-bit integer versions, and also several versions using 64-bit double precision floating point values for comparison.

The following table consists of some timings of our modular Hessenberg algorithm for a sparse 364×364 input matrix arising from an application in combinatorics. See [6]:

Representation of values	time (secs) ¹	time (secs) ²	time (secs) ³
1. 64-bit integer	132.4	100.7	109.7
2. 32-bit integer	48.2	68.4	45.7
3. 64-bit float using <i>fmod()</i>	58.7	22.3	140.9
4. 64-bit float using <i>floor()</i> with fix	46.2	42.2	49.8
5. 64-bit float using <i>floor()</i> without fix	38.8	36.3	42.0
6. Berkowitz algorithm	2470.2	2053.6	1886.2

Explanations of the different representations of values:

1. The 64-bit integer version is implemented using the *long long int* datatype in C, or equivalently the *integer[8]* datatype in Maple. All modular arithmetic is first being done by executing the corresponding operation, then taking the result mod p because we work in \mathbb{Z}_p . In order to compute the inverses mod p , we have implemented the half extended Euclidean Algorithm in C.
2. The 32-bit integer version is similar, but implemented using the *long int* datatype in C, or equivalently the *integer[4]* datatype in Maple.
3. The 64-bit float using *fmod()* version is implemented using the *double* datatype in C, or equivalently the *float[8]* datatype in Maple. This works because floating point numbers are stored as mantissa and exponent, thus any integer a with $a^2 \leq B^2$ can be represented exactly as a 64-bit floating point number. Operations such as additions, subtractions, multiplications are followed by a call to *fmod()* to reduce the results mod p , since we are working in \mathbb{Z}_p .

¹Intel Xeon 2.0 GHz 32-bit processor

²Operon 246 2.0 GHz 64-bit processor

³Optipex Pentium IV 3 GHz 32-bit processor

4. The 64-bit float using $\text{floor}()$ with fix version is similar to above, but uses $\text{floor}()$ instead of $\text{fmod}()$. To compute $b \leftarrow a \bmod p$, we first compute $c \leftarrow a - p \times \lfloor a/p \rfloor$, then $b \leftarrow c$ if $c \neq p$, $b \leftarrow 0$ otherwise.
5. The 64-bit float using $\text{floor}()$ without fix vision is similar to above, but does not do the extra check for equality to p at the end. So to compute $b \leftarrow a \bmod p$, we actually compute $b \leftarrow a - p \times \lfloor a/p \rfloor$, which results in $0 \leq b \leq p$.

Asymptotic Comparison of the Methods

Let A be an $n \times n$ matrix of integers. To compare the running times of the two algorithms, we suppose that the entries of A are bounded by B^m in magnitude, that is, they are m base B digits in length. For both algorithms, we need a bound on the size of the coefficients of the characteristic polynomial $c(x)$. A generic bound on the size of the determinant of A is sufficient since this is the largest coefficient of $c(x)$. The magnitude of the determinant of A is bounded by $M = n!B^{mn}$ and its length is bounded by $n \log_B n + mn$ base B digits. If $B > 2^{15}$ then we may assume $\log_B n < 2$ in practice and hence the length of the determinant is $O(mn)$ base B digits.

In Berkowitz's algorithm, the $O(n^4)$ integer multiplications are on integers of average size $O(mn)$ digits in length, hence the complexity (assuming classical integer arithmetic is used) is $O(n^4(mn)^2)$. Since Maple 9 uses the FFT for integer multiplication and division, the complexity is reduced to $\tilde{O}(n^5m)$.

In the modular algorithm, we will need $O(mn)$ machine primes. The cost of reducing the n^2 integers in A modulo one prime is $O(mn^2)$. The cost of computing the characteristic polynomial modulo each prime p is $O(n^3)$. The cost of the Chinese remaindering assuming a classical method for the Chinese remainder algorithm (which is what Maple uses) is $O(n(mn)^2)$. Thus the total complexity is $O(mn^2 + mnn^3 + n(mn)^2) = O(m^2n^3 + mn^4)$.

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